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The Pennsylvania Defoliation Application Pilot Test

R.G. McLeod A.L. Zobrist

N.A. Bryant



September 15, 1983

NASA

National Aeronautics and Space Administration

Jet Propulsion Laboratory California Institute of Technology Pasadena, California

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ABSTRACT

Satellite imagery for the State of Pennsylvania was digitally mosaicked to provide the seed data base for monitoring defoliation of hardwood trees by the gypsy moth. Two separate mosaics for the state were prepared, one before defoliation and one after defoliation, to determine the extent, direction, and impact of gypsy moth activity in the state. The digital mosaic technology used to construct the data base was transferred to Pennsylvania State University to permit periodic updates to the data base and to assist in planning and abatement activities. Participating agencies or institutions included Goddard Space Flight Center and the Pennsylvania State University Office for Remote Sensing of Earth Resources.

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1. OVERVIEW

This report documents the efforts expended at JPL in providing image processing support to the Pennsylvania Defoliation Applications Pilot Test (APT) sponsored by NASA and Goddard Space Flight Center. The objectives of the JPL task were as follows:

- A.1) Phase I <u>Testing</u> Geometrically correct all four bands of two 1979 Landsat scenes of the Harrisburg, PA. area to a Universal Transverse Mercator (UTM) map projection; digitally mosaic all four bands.
- A.2) Register classified imagery derived from the 1979 Landsat data to the four-band Landsat mosaic created in A.1 above.
- A.3) Register two alternate-date Landsat scenes to the 1979 map-projected Landsat scenes to test a change-detection procedure.
- B.1) Phase II <u>Implementation</u> Geometrically correct all four bands of twelve 1979 time frame Landsat scenes of the entire state of Pennsylvania to a UTM projection; digitally mosaic all four bands.
- B.2) Register multispectrally classified imagery derived from the 1979 time frame imagery for the entire state to the four-band Landsat mosaic created in B.1 above.
- B.3) Register twelve 1981 Landsat scenes for the entire state to the 1979 digital mosaic data base.
- C.1) Phase III <u>Reporting</u> Compile technical report on the software and procedures used in providing assistance to the APT.
- C.2) Transfer and install all relevant software needed for updating the mosaic data bases to Pennsylvania State University for operational use.

Plate I summarizes the task overview.

Pennsylvania Mosaic Task Overview

Phase I Test and Evaluation

- 1. Two-frame test mosaic
- 2. Classify to forest/nonforest
- 3. Two-frame test mosaic; different date; same area
- 4. Register two-date/two-frame mosaics to detect change in forested areas

Phase II Implementation

- Ten-frame mosaic of entire state;
 1979 time frame data; two UTM zones
- 2. Classify to forest/nonforest
- 3. Ten-frame mosaic of entire state; 1981 time frame data; two UTM zones
- 4. Register two-date/ten-frame mosaics to detect change in forested areas

Phase III Reporting

- Transfer capability and software to Pennsylvania State University
- 2. Document procedures used in the task

Plate I

2. INTRODUCTION

Since its introduction from Europe into Massachusetts in the late 1860s, the gypsy moth Lymantria dispar (L.), has repeatedly defoliated hundreds of thousands of hectares of forest. The mature gypsy moth caterpillar is about 5 to 7 cm (2 to 3 in.) in length, and as many as 30,000 of these caterpillars can infest a single tree. Each caterpillar can consume up to ten small leaves a day [1]. Over the past ten years, the State of Pennsylvania has attributed the loss of \$32 million dollars worth of timber resources to this pest. The insect does not kill the tree immediately, but after prolonged infestations over several years the tree is destroyed. While the natural spread of the gypsy moth is slow, its spread can accelerate because of its ability to hitchhike with people traveling through infested areas.

In order to plan appropriate pest management activities, resource managers must continually monitor the movements and damage caused by this insect. Over large geographic areas, conventional methods of surveillance such as field site visits and large-scale aerial photography are expensive and time consuming. Alternative methods of assessment must be developed that are inexpensive, timely, and mesh well with current practices.

Developing new assessment methods for gypsy moth infestations is the goal of the Pennsylvania Defoliation Applications Pilot Test (APT), a joint study by Goddard Space Flight Center/NASA and Pennsylvania State University. These new methods being developed are to be transferred to the Pennsylvania Division of Forest Pest Management, Bureau of Forestry, for implementation to operational use.

2.1 Basic Procedure

The basic procedure is to utilize multidate Landsat imagery to monitor the infestations [2]. An image is acquired of an area prior to infestation, and it is classified, using computer aided analysis techniques, to identify the extent of forest cover versus nonforest cover. After insect damage, a second

image of the same area is obtained and it is digitally overlaid onto the forest cover map derived from the initial image. Forested areas exhibiting defoliation can then be identified and tabulated. Hectare counts and estimates can be generated and abatement procedures or strategies developed.

While Landsat is a convenient and relatively inexpensive source of data, certain properties associated with the data present problems. The framing convention of the Landsat sensor does not lend itself well to imaging entire states in a single scene. To increase the utility of the data, the Landsat frames must be geometrically corrected to a standard map projection and then mosaicked.

3. IMAGE PROCESSING ENVIRONMENT

All data processing performed at JPL utilized the Image Processing Laboratory (IPL). The current IPL configuration includes an IBM 370/158 mainframe computer with 8 megabytes of memory, eight tape drives [(six 9-track, 314- and 629-bit/cm (800- and 1600-bit/in.); two 7-track, 88-, 218-, and 314-bit/cm (225-, 550-, and 800-bit/in.)], and 3.8 gigabytes of on-line disk storage. The disk storage consists of 8 CDC model 3350 high-speed, permanently mounted disks, and two CDC 3330-ll mountable disks. An interactive environment is supported by TSO, LIBEXEC and image display devices. Image displays include a Ramtek 6400 display system that accommodates 6-bit black and white imagery of any dimension within a 640 x 512 element window. A COMTAL 8000 display unit is used to display 8-bit black and white imagery up to 1024 x 1024 elements. Color display is accomplished with two separate systems. A COMTAL 8003 System provides 512 x 512 element resolution for 8-bit three color (RGB) images and a DeAnza provides expanded 512 x 512 element display capability. A laser film recorder and DICOMED D-64 devices are used for film playback.

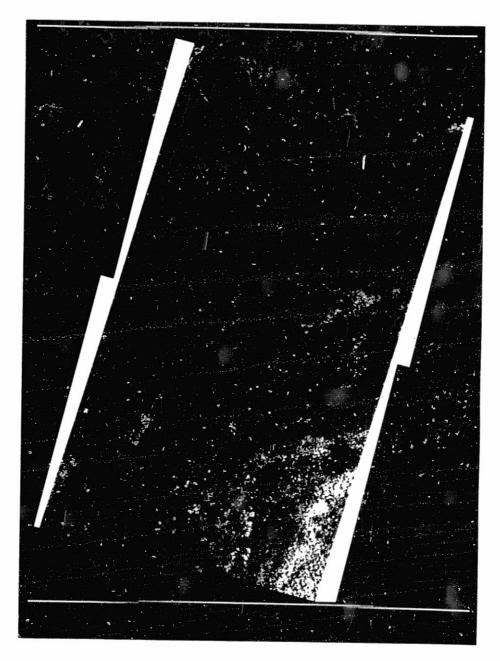
The IPL also maintains a complete library of over 300 special purpose image processing applications programs. The system in use is the Video Image Communication and Retrieval (VICAR) and the Image Based Information System (IBIS) developed at JPL [3,4].

4. PHASE I: TEST AND EVALUATION OF PROCEDURES

Prototyping a mosaicking procedure for a particular application is a difficult and time consuming task. All scenes used must be logged and inspected, data sets and tapes allocated, mapping grids defined, and software procedures developed, exercised, and verified. Phase I of the project was designed to meet two needs: Firstly, a test case was performed to illustrate the capability of the technology for digital mosaics. In the process of demonstrating the capability, the technical procedures needed to accomplish the task were refined, streamlined and made error-free. Secondly, interim products documenting the process were produced that showed capability of procedures developed, and provided initial data for GSFC to begin procedure building for processing at GSFC. The procedures developed for the mosaicking process are described in detail under Phase II.

Phase I mosaic utilized two Landsat frames in order to test and evaluate the technology. A two-frame mosaic was compiled from 1979 data. The frames were acquired on the same day and were in a common path [(i.e., top-to-bottom relationship), see Table 1.] Figure 1 depicts the resultant mosaic. In the second part of the testing phase, Landsat data of an alternate date (1978) was mosaicked (see Table 1) and registered to the initial mosaic data base. A multispectral classification of the initial 1979 image data was performed at GSFC and resulted in a forest cover vs. nonforest cover confidence map which was used as a stratification in a later classification to display gypsy moth induced defoliation. The confidence map was then registered to the initial and subsequent mosaic. It was found that while some errors in first date to second date registration occurred, it was felt that with a sufficiently dense network of tiepoints which control the geometric registration, a suitable tolerance in registration could be achieved.

	PHASE I LANDSAT SCENES
1979 Mosaic Base	Landsat World Reference System Area 1 30478-15123 Path 17 Row 31 Williamsport 2 30478-15130 Path 17 Row 32 Harrisburg Both images acquired 26 June 1979
1978 Mosale Base	1 30208-15135 Path 17 Row 31 Williamsport 2 30208-15141 Path 17 Row 32 Harrisburg Both images acquired 29 Sept. 1978



Test and Evaluation Phase Product Output

A two-frame Landsat mosaic of data gathered on June 26, 1979, and from a common path was constructed. This image is 3700 lines by 2900 samples.

Figure 1

5. PHASE II: IMPLEMENTATION: PREPARATION OF THE DIGITAL MOSAICS

The Landsat data tapes used for Phase II, a mosaic prior to defoliation, were delivered to JPL by Goddard Space Flight Center. Goddard ordered the scenes from EROS Data Center in order to proceed in a parallel effort with other aspects of the project. Table 2 depicts the Landsat frames used in this mosaic, and Figure 2 shows the individual footprint of each scene for the state.

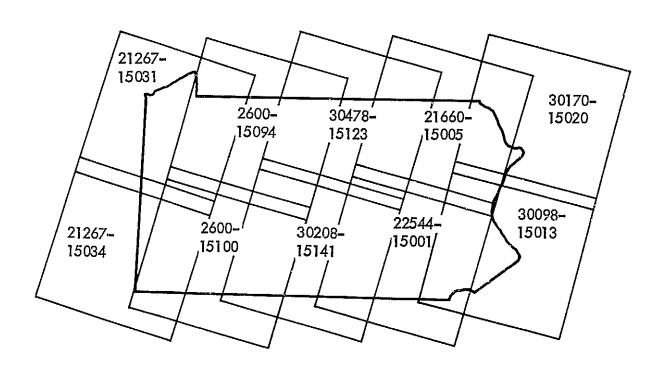
TABLE 2

PHASE II LANDSAT SCENES							
PATH	ROW	SCENE IDENTIFICATION	LOCATION NAME	DATE			
19	31	21267-15031	Titusville	July 12, 1978			
19	32	21267-15034	Steubenville	July 12, 1978			
18	31	2600-15094	Warren	September 13, 1976			
18	32	260015100	Pittsburgh	September 13, 1976			
17	31	30478-15123	Williamsport	June 26, 1979			
17	32	30208-15141	Harrisburg	September 29, 1978			
16	31	21660-15005	Scranton	August 9, 1979			
16	32	2544-15001	Lebanon	July 19, 1976			
15	31	30170-15020	Poughkeepsie	August 22, 1978			
15	32	30098-15013	Trenton	June 11, 1978			

5.1 Logging the Initial Scenes

The Landsat data were initially logged to be compatible with the VICAR format and system requirements at IPL. The logging consists of a series of separate steps depending upon the type of data ordered. Since February 1979, imagery processed by EROS Data Center is in band sequential format with major geometric corrections. If the data are processed prior to that date, the data

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Landsat Frames Footprints
Depicted here are the individual footprints
of each scene used for the mosaic Phase II.

Figure 2

are band interleaved by pixel pairs with no geometric corrections performed. Typical of almost all applications involving this type of imagery, it is necessary to select acquisition dates spanning over a long period of time to obtain the most cloud-free coverage possible. Hence, it was necessary to use both band-sequential and band-interleaved formats as basic data input for the task.

Imagery processed since February 1979 is fairly easy and inexpensive to log because no geometry changes are necessary, at least in the first phases of the mosaicking process. Extraneous engineering files are stripped off and a VICAR label attached to the image files to be used by subsequent VICAR modules. The uncorrected data, band interleaved by pixel pairs, require extended effort and expense to produce a data format suitable for the VICAR mosaicking process. Nominal geometric and radiometric corrections include removal of earth rotation induced skew, panorama effect, and mirror scan velocity profile (MSVP) compensation. The pixel size at this stage of the processing is the instantaneous field of view (IFOV) of 57 and 79 meters.

Figures 3 through 12 depict the logged Landsat scenes used for the early date Phase II mosaic.

5.2 Map Base

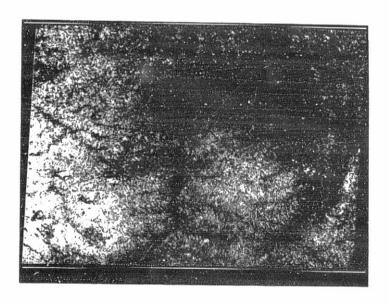
The Universal Transverse Mercator (UTM) Projection was chosen as the mapping base for the mosaic. It was decided to select a pixel size of 57 meters by 57 meters because of the IFOV sampling interval along the Landsat scan line. Selection of a 50-meter pixel size would have allowed the data to be extracted from the UTM grid more conveniently, but would also have increased the amount of data to be processed while not increasing the information content.

The State of Pennsylvania covers about 6 degrees of longitude, large enough to encompass one UTM zone. Unfortunately, the state straddles a UTM zone boundary which bisects the state into western and eastern zones, Zone 17 and Zone 18, respectively. To preserve map projection properties and to provide

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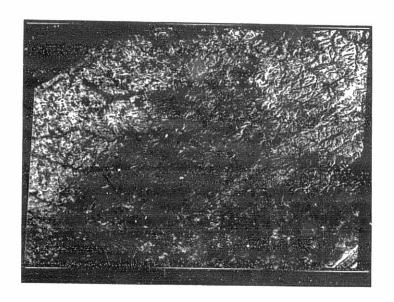


Frame 1 Titusville 21267-15031 Figure 3

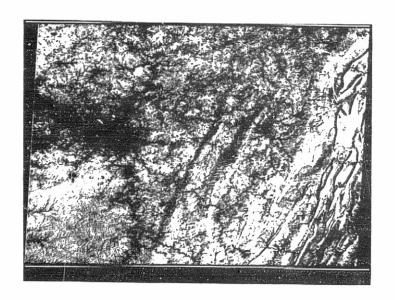


Frame 2 Steubenville 21267-15034 Figure 4

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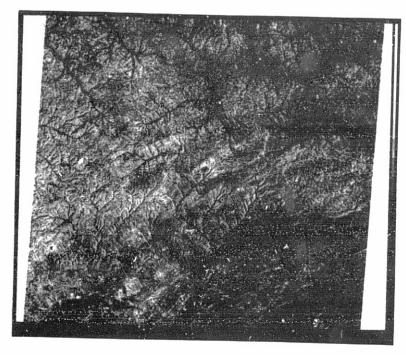


Frame 3 Warren 2600-15094 Figure 5

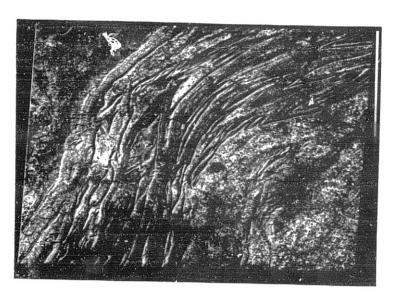


Frame 4 Pittsburg 2600-15100 Figure 6

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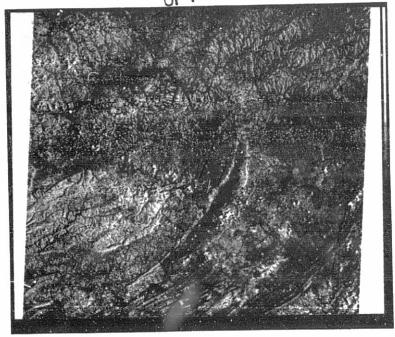


Frame 5 Williamsport 30478-15123 Figure 7

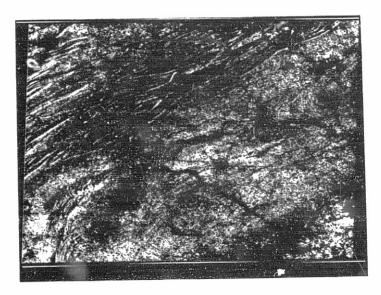


Frame 6 Harrisburg 30208-15141 Figure 8

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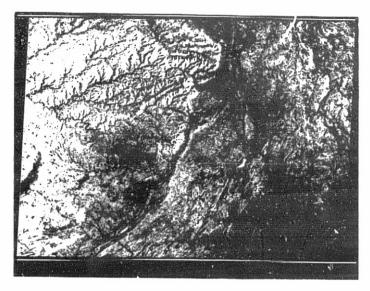


Frame 7 Scranton 21660-15005 Figure 9

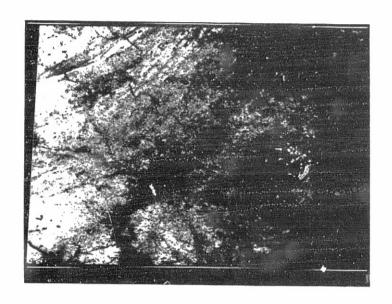


Frame 8 Lebanon 2544-15001 Figure 10

OPPORTAL DESTRUCTION OF PROOF COLUMN



Frame 9 Poughkeepsie 30170-15020 Figure 11



Frame 10 Trenton 30098-15013 Figure 12

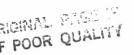
consistency with subsequent data sets to be registered to the Landsat mosaic data base, two separate mosaics were constructed, one for each zone. Coverage of the entire state with Landsat data can be met with ten scenes, but because of the two map projection zones, six scenes were mosaicked for each zone, with the two central scenes contributing data to each zone. In effect, two six-frame mosaics were constructed for this task.

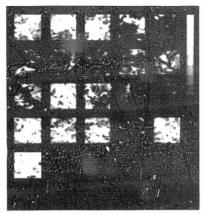
The mapping grid was configured so that the imagery would resample to the selected scale of 57 meters and rotated north assuring the data rasters would be aligned east-west relative to the mapping grid. The advantages of this technique are fairly straightforward. First, the data are displayed in a familiar fashion with north at the top, and second, map quadrangles can be extracted from the data base with a minimum of wasted storage space that results from rotation.

5.3 Planimetric Control

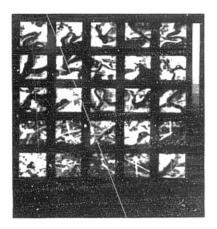
Planimetric control for remotely sensed imagery in a mosaicking context can be obtained in several ways. If the exposure or acquisition time of the scene is short enough, such as in a framing-type sensor, calibration and control of the data using spacecraft emphemeris information is often sufficient. Since the scene acquisition time for the Landsat image is on the order of 27 seconds, and because it is a scanning-type sensor, it is necessary to incorporate known geodetic points on the surface of the earth. Information obtained from the Control Point Library Building System (CPLBS) was used to provide planimetric control to each Landsat scene as each fits into the mosaic [5].

The information from the CPLBS consists of a 32-pixel by 32-pixel image chip containing a geographic feature, e.g., a road intersection or river bend, as well as the latitude and longitude of the feature. Additional engineering data regarding the Landsat band and which satellite the image chip was taken from is also included. The accuracy of the point is generally within 20 meters. Figures 13 through 22 are the CPLBS files in image format for the images in Pennsylvania.

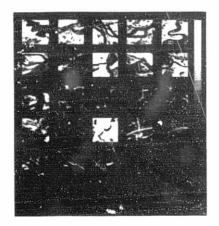




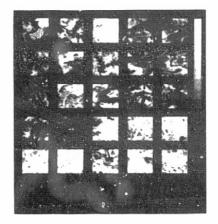
CPLBS File for Path 19 Row 31 TITUSVILLE Figure 13



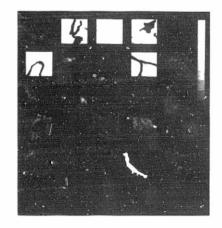
CPLBS File for Path 18 Row 31 WARREN Figure 15



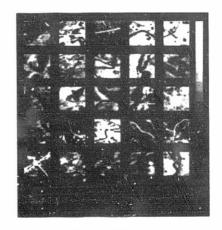
CPLBS File for Path 17 Row 31 WILLIAMSPORT Figure 17



CPLBS File for Path 19 Row 32 STEUBENVILLE Figure 14

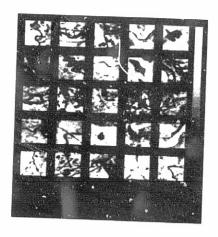


CPLBS File for Path 18 Row 32 PITTSBURG Figure 16

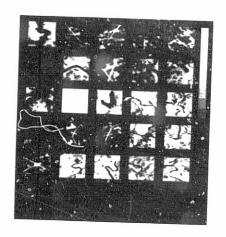


CPLBS File for Path 17 Row 32 HARRISBURG Figure 18

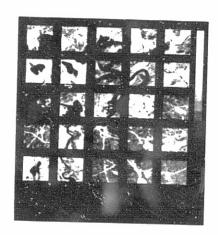
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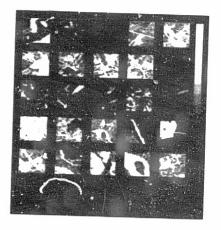
CPLBS File for Path 16 Row 31 SCRANTON Figure 19



CPLBS File for Path 16 Row 32 LEBANON Figure 20



CPLBS File for Path 15 Row 31 POUGHKEEPSIE Figure 21



CPLBS File for Path 15 Row 32 TRENTON Figure 22

Image correlation is performed using the two-dimensional fast Fourier transform (2D FFT) computational method to relate ground control points (GCPs) from the CPLBS with the associated locations in each Landsat scene [6]. To initiate the correlation procedure, three points are first identified in the Landsat scene that can also be found on a map. This process is usually done on an interactive display system with the line/sample coordinates found using a trackball cursor. The latitude and longitude of that point are read directly from the map. The three points are used to determine an affine surface that is used as an estimator of where the 2D FFT correlation routine is to search in the image to match a particular GCP. While the affine fit does not give the true location within a pixel (or several pixels), it does provide the search algorithm with a reasonable window in which to search. As good correlations are obtained, the surface is refined so that less searching is required as the algorithm proceeds through the GCP file.

There are several problems associated with using a preestablished ground control point file for image registration. First and foremost, the file has to be built, a large effort that has been expended by NASA and IBM. The file also has to be continuously updated because of changes in the ground scenes and the varying conditions of the imagery. A particularly difficult problem in the mosaic registration and control effort was trying to correlate the GCPs with Landsat scenes that were acquired over several seasons. The ground reflectance changes that occur from season to season impair the correlation performance. As an example, a stream course feature in GCP may be highly recognizable in a particular season, but when examining the scene it is being correlated with, the stream may be silted and the surrounding land cover blends in with the stream creating a low variance, and hence a low information content image. This makes it difficult to correlate all the GCPs selected for that particular path/row. At most, 18 of the 25 GCPs for each path/row were correlated for the Pennsylvania mosaic.

The ground control points correlated with the Landsat scenes used for the mosaic give each scene its position and projection in the global mapping output grid. If each scene were corrected and inserted into the grid with

only the GCPs as control, overall planimetric accuracy would be within prescribed tolerances but in all likelihood the edges between the neighboring frames would not match perfectly. To remedy this situation, a series of edge matching points is correlated in all overlapping areas of all scenes used. These points are then mapped (controlled) by the GCPs. The net effect of these additional points is to eliminate any side-to-side or top-to-bottom mismatch between scenes.

Information in the overlap area regarding brightness is also obtained and used to radiometrically correct the imagery at the same time that geometry changes are made. Difficulties in matching neighboring scenes radiometrically were experienced during the processing. With haze problems and the varying dates of the imagery, it was possible with existing software to match the brightness but not variance of average areas. With variance differences not resolved, marked divisions between scenes may occur.

The early date mosaic was completed in two stages. Separate control point files and mapping were used for UTM Zone 17 and UTM Zone 18. The resultant 'halves' of the mosaic for the state were each 6500 lines by 8500 samples. All four Landsat bands were corrected. These data were then mosaicked and segmented into the 1-degree by 2-degree quadrangles.

Quadrangle configurations and specifications for the Pennsylvania mosaic are listed in Table 3. Band 6 Landsat imagery for the Pennsylvania quadrangles (UTM Zones 17 and 18) is presented in Figures 23 through 30.

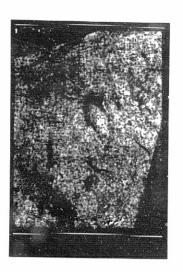
TABLE 3

QUADRANGLE CONFIGURATION PENNSYLVANIA MOSAIC <u>UTM Zone 17</u>

QUAD	<u>NAME</u>	<u>SERIES</u>	TYPE	UPPER LEFT CORNER	LOWER RT. CORNER	NL.*	NS*		
1 2 3 4	Cleveland Canton Warren Pittsburgh	NK17-8 NK17-11 NK17-19 NK17-12	1°x1°long 1°x2° 1°x2°long	42°N 81°W 42°N 81°W 42°N 80°W 41°N 80°W	41°N 80°W 41°N 80°W 41°N 78°W 39.5°N 78°W	2000 3000 2100 3100	1500 1600 3000 3100		
UTM Zone 18									
5 6 7 8	Williamspor Harrisburg Seranton Newark	NK18-10 NK18-8	1°x2° 1°x2°long 1°x2°	42°N 78°W 41°N 78°W 42°N 76°W 41°N 76°W	41°N 76°W 41°N 76°W 41°N 76°W 39°5°N 74°W	2100 3100 2000 3000	3000 3100 3000 3100		

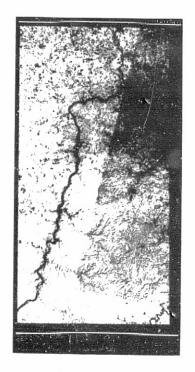
^{*}NL = number of lines (records) in image

^{*}NS = number of samples (bytes) per line



Cleveland NK17-8; 1° x 1° quadrangle of Band 6 Landsat imagery. This image is 2000 lines by 1500 samples.

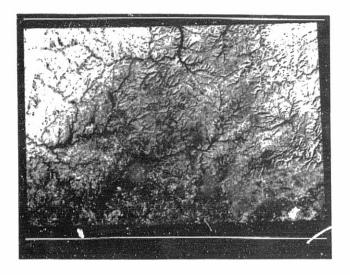
Figure 23



<u>Canton NK17-11</u>; 1° x 1° quadrangle of Band 6 Landsat imagery. This image is 3000 lines by 1600 samples.

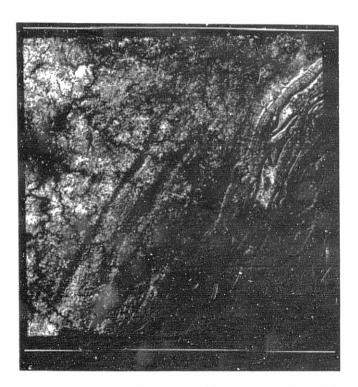
Figure 24

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Warren NK17-9; 1° x 2° quadrangle of Band 6 Landsat imagery. This image is 2100 lines by 3000 samples.

Figure 25



<u>Pittsburgh NK17-12</u>; 1° x 2-1/2° quadrangle of Band 6 Landsat imagery. This image is 3100 lines by 3100 samples.

Figure 26

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<u>Williamsport NK18-7</u>; 1° x 2° quadrangle of Band 6 Landsat imagery. This image is 2100 lines by 3000 samples.

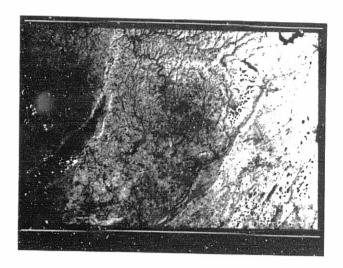
Figure 27



<u>Harrisburg NK18-10</u>; 1° x 2-1/2° quadrangle of Band 6 Landsat imagery. This image is 3100 lines by 3100 samples.

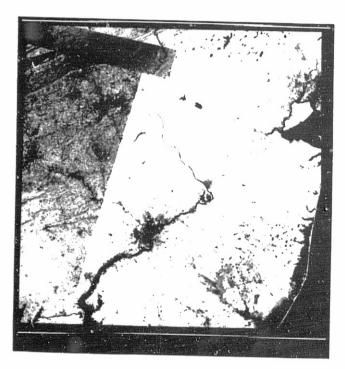
Figure 28

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Scranton NK18-8; 1° x 2° quadrangle of Band 6 Landsat imagery. This image is 2000 lines by 3000 samples.

Figure 29



Newark NK18-11; 1° x 2-1/2° quadrangle of Band 6 Landsat imagery. This image is 3000 lines by 3100 samples.

Figure 30

5.4 Forest/Nonforest Mosaic

In a parallel effort, Goddard Space Flight Center personnel applied multispectral classification techniques to the unprocessed Landsat scenes that were used as input for the early data mosaic. One file of data depicting forest and nonforest land cover was derived and sent to JPL to be registered with the mosaic data base. Since the classification was derived from the 'raw' unlogged data, logging was performed using nearest neighbor interpolation to make the nominal geometric adjustments and then geometrically corrected a second time with nearest neighbor interpolation using the control points produced for the early date mosaic. These data were then mosaicked and segmented into the 1° x 2° quadrangles.

5.5 Late Date Mosaic - Postdefoliation

Requirements for this task in Phase III stipulated that once the base mosaicking was completed for the entire state, the technology to update the mosaic on a yearly basis be transferred to the State of Pennsylvania. The VICAR/IBIS software system was obtained from COSMIC by the Office of Remote Sensing of Earth Resources (ORSER) at Pennsylvania State University. In early 1982 the system was installed and tested. Additional program modules needed to produce update mosaics were also delivered, installed, and tested. Once the system was running, a test mosaic was attempted with several goals in mind. First, it was necessary to initiate the ORSER staff in the functions and operation of the VICAR system with regard to mosaicking applications. Second, the Pennsylvania State computer system exercised VICAR to isolate problems peculiar to the facility. Finally, a prototype procedure for actually creating update mosaics had to be generated and an application case performed.

Both the late date and early date mosaics had to be generated in two sections, one section for each UTM zone in the state. In order to ease scheduling difficulties and to provide Penn State ORSER staff with mosaicking experience, a parallel effort was undertaken with the update mosaic for UTM Zone 17 being

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generated at JPL and the update mosaic for UTM Zone 18 generated at ORSER. This effort satisfied technology transfer requirements for Phase III of the task.

The Landsat scenes used in the UTM Zone 17 update mosaic were, fortunately, in the EDIPS format, easing preprocessing efforts. Table 4 depicts the scenes used in the update mosaic. Since the second date imagery is registered to the early date mosaic, the resultant products are identical to the original mosaic, except for ground cover changes. The update mosaics dimensions are the same as the early date mosaic, 6500 lines by 8500 samples, and it is also segmented into the requisite quadrangles (Table 3). The completed composite of the Pennsylvania mosaic, UTM Zones 17 and 18, is shown in Figures 31 and 32.

TABLE 4

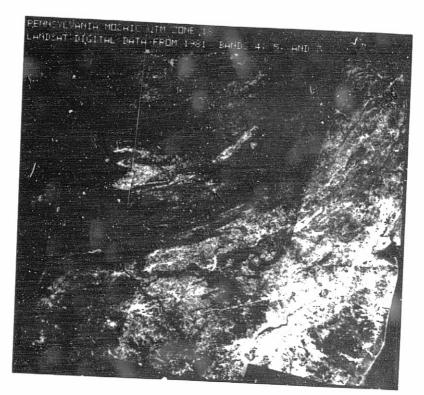
	LAN	DSAT SCENES USED IN UTM	ZONE 17 UPDATE I	MOSAIC
PATH	ROW	SCENE IDENTIFICATION	LOCATION NAME	DATE
19	31	22311-15214	Titusville	May 24, 1981
19	32	22311-15220	Steubenville	May 24, 1981
18	31	22400-15142	Warren	August 18, 1981
18	32	22400-15144	Pittsburgh	August 18, 1981
17	31	22381-15084	Williamsport	July 30, 1981
17	32	22381-15090	Harrisburg	July 30, 1981



UTM Zone 17 Mosaic, 1981. This image is a black and white composite of Landsat bands 4, 5, and 7. These data were reduced to 114-meter pixels to allow playback on the film recorder. The resultant image is 3250 lines by 4250 samples.

Figure 31

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UTM Zone 18 Mosaic, 1981. This image is a black and white composite of Landsat bands 4, 5, and 7. These data were reduced to 114-meter pixels to allow playback on the film recorder. The resultant image is smaller (2625 lines and 3050 samples) than UTM Zone 17 because data outside the Pennsylvania State borders were removed to conserve storage space.

Figure 32

TECHNICAL DISCUSSION: MOSAICKING PROCESS

6.1 <u>Tiepoint File Initialization</u>

Tiepoint file organization is an important component of the mosaicking process. Tiepoints previously discussed such as ground control points and edge matching points require strict and consistent naming labels not only for use in procedures but also for bookkeeping within the system catalog. While the tiepoint files contain the locational information, additional information is appended to each file to be used as diagnostics in compiling the master correction file. Additional information such as sequence numbers, correlation value, and type of tiepoint (ground control or edge) is added. Sections 6.1.1 through 6.1.3 show the files allocated for use in the mosaic process at IPL.

6.1.1 <u>UTM Zone 17</u>

6.1.1.1 Ground Control Points (obtained from CPLBS)

RGM900.PAT1	This file contains line and sample in the original Landsat
PAT2	image with the corresponding latitude and longitude. Each
PAT3	number at the end of the data set name refers to the frame
PAT4	to which the data set pertains.
PAT5	
PAT6	Data set size is 3600 bytes x 1 record.
RGM900.PAT1x1	This file contains line and sample values of original
PAT2x2	Landsat and corresponding line, and a sample in the output
PAT3x3	grid. These points are map projected to UTM Zone 17.
PAT4x4	Each number at the end of each data set name refers to the
PAT5x5	frame numer to which the data set pertains.
PAT6x6	Data set size is 3600 bytes x 1 record.

(Frame numbers for UTM Zone 17 and UTM Zone 18 are 1 through 6 and 5 through 10, respectively; frame numbers for UTM Zone 17 second date are 11 through 16).

6.1.1.2 Edge Matching Points

RGM900.PAT1x2 This file contains line and sample in the original Landsat PAT1x3 images for neighboring frames. For example, data set PAT1x4 RGM900.PAT1x2 contains points common to frame 1 and frame PAT2x4 2. Additional information includes correlation values for PAT3x4 each point and a sequence number for identification.

PAT3x6 PAT4x6

Data set size is 3600 bytes x 5 records.

6.1.1.3 Perimeter File

PAT5x6

RGM900.PATCUT

This file contains perimeter information for each frame and is used in selecting edge matching points as well as in the final correction phase. Specific information includes the sequence, frame number, and vertices for a user defined contour along which tiepoints are selected. Data set size is 1200 bytes x 12 records.

6.1.1.4 <u>Label Verification File</u>

RGM900.PATVFY

This data set is used for checking the header labels to insure that the correct image file is being processed. Information includes frame acquisition number, frame title, and spectral band.

Data set size is 360 bytes x 10 records.

6.1.1.5 Master Tiepoint Files

This file contains information for raw tiepoints for all RGM900.PATZ17L

frame-pairs and neighbors. Frame number, sequences, tiepoint type, line, sample, initial Z value, and correlation

value are included.

Data set size is 360 bytes x 360 records.

RGM900.PATZ17M

This file contains the same information as the 'PATZ17L' file. This version is edited and operated on to produce the final tiepoints used for frame correction.

Data set size is 360 bytes x 300 records.

6.1.2 UTM Zone 17, Second Date: 1981

6.1.2.1 Ground Control Points (correlation matches obtained between first second dates)

RGM900.PAT11	This file contains line and sample in the original Landsat
PAT12	image with the corresponding line and sample in the
PAT13	update frames. Each number at the end of the data set
PAT14	name refers to the frame to which the data set pertains.
PAT15	
PAT16	Data set size is 3600 bytes x 1 record.

This file contains line and sample values of original RGM900.PAT11x11 Landsat and corresponding line and sample in the output PAT12x12 grid. These points are map projected to UTM Zone 17 by PAT13x13 virtue of being chosen from the first date UTM Zone 17 PAT14x14 mosaic frames. Each number at the end of each data set PAT15x15 name refers to the frame number to which the data set PAT16x16 pertains.

Data set size is 3600 bytes x 1 record.

6.1.2.2 Edge Matching Points

RGM900.PAT11x12 This file contains line and sample in the original Land-PAT11x13 sat images for neighboring frames. For example, data set RGM900.PAT1x2 contains points common to frame 11 and frame PAT12x14 12. Additional information includes correlation values PAT13x14 for each point and a sequence number for identification.

PAT13x15
PAT13x16
PAT14x16

PAT15x16 Data set size is 3600 bytes x 5 records.

6.1.2.3 Perimeter File

RGM900.PATCUT

This file contains perimeter information for each frame and is used in selecting edge matching points as well as in the final correction phase. Specific information includes the sequence, frame number, and vertices for a user defined contour along which tiepoints are selected.

Data set size is 1200 bytes x 12 records.

6.1.2.4 <u>Label Verification File</u>

RGM900.PATVFY

This data set is used for checking the header labels to insure that the correct image file is being processed. Information includes frame acquisition number, frame title, and spectral band.

Data set size is 360 bytes x 10 records.

6.1.2.5 Master Tiepoint Files

RGM900.PATZ172L This file contains information for raw tiepoints for all frame pairs, and neighbors. Frame number, sequences, tiepoint type, line, sample, initial Z value, and correlation value are included.

Data set size is 360 bytes x 360 records.

RGM900.PATZ172M This file contains the same information as the 'PATZ172L' file. This version is edited and operated on to produce the final tiepoints used for frame correction.

Data set size is 360 bytes x 300 records.

6.1.3 <u>UTM Zone 18</u>

6.1.3.1 Ground Control Points (obtained from CPLBS)

RGM900.PAT5	This file contains line and sample in the original Land-
PAT6	sat image with the corresponding latitude and longitude.
PAT7	Each number at the end of the data set name refers to the
PAT8	frame to which the data set pertains.
PAT9	
PAT10	Data set size is 3600 bytes x 1 record.
RGM900.PAT5x5	This file contains line, sample values of original Land-
PAT6x6	sat, and corresponding line and sample in the output
PAT7x7	grid. These points are map projected to UTM Zone 18.
PAT8x8	Each number at the end of each data set name refers to the
PAT9x9	frame number to which the data set pertains.
PAT10x10	Data set size is 3600 bytes x 1 record.

6.1.3.2 Edge Matching Points

RGM900.PAT5x6

This file contains line and sample in the original LandPAT5x7

sat images for neighboring frames. For example, data set
PAT5x8

RGM900.PAT5x6 contains points common to frame 5 and frame
PAT6x8

6. Additional information includes correlation values for
PAT7x8

each point and a sequence number for identification.

PAT7x9

PAT7x10

PAT8x10

PAT9x10

Data set size is 3600 bytes x 5 records.

6.1.3.3 Perimeter File

RGM900.PATCUT

This file contains perimeter information for each frame and is used in selecting edge matching points as well as in the final correction phase. Specific information includes the sequence, frame number, and vertices for a user defined contour along which tiepoints are selected. Data set size is 1200 bytes x 12 records.

6.1.3.4 Label Verification File

RGM900.PATVFY

This data set is used for checking the header labels to insure that the correct image file is being processed. Information includes frame acquisition number, frame title, and spectral band.

Data set size is 360 bytes x 10 records.

6.1.3.5 Master Tiepoint Files

RGM900.PATZ18L

This file contains information for raw tiepoints for all frame pairs and neighbors. Frame number, sequences, tiepoint type, line, sample, initial Z value, and correlation value are included.

Data set size is 360 bytes x 360 records.

RGM900.PATZ18M

This file contains the same information as the 'PATZ18L' file. This version is edited and operated on to produce the final tiepoints used for frame correction.

Data set size is 360 bytes x 300 records.

6.2 Edge Point Selection Process

In order to insure that separate scenes register without any apparent mismatch, a series of edge registration points are selected. There is a basic philosophy involved here in which two types of tiepoints are used. Manually selected ground control points establish absolute control to a map base. If each scene were corrected independently using only the ground control points, fitting the processed scenes together would not be possible without producing seams. The edge matching points merge the discontinuities so that a smooth geometric seam boundary is obtained.

6.2.1 <u>Definition of Perimeter File</u>

The first step in selecting common points between neighboring Landsat frames is to define a perimeter file around each image. The perimeter is usually chosen to reside within 100 pixels from the edge of the image. With the information in the file, common points can be selected along the line or reasonably close to the line. The advantage lies in that all image data

outside the perimeter can be discarded after processing and thus insuring that scene boundaries are exactly at the tiepoint locations. The only possible way for geometric seams to occur is to have erroneous tiepoints in the correction file.

6.2.2 Three-Point Fit

In order to establish a rough relationship between neighboring scenes, three existing ground control points (either derived from correlations of the CPBLS or manual) are selected to compute an affine surface fit. A plane is fitted for each neighbor pair. The information from this operation is used to direct the correlation routine where to search for tiepoints in each scene. Once the routine knows where to search, the selection process is incremented in 100 pixel intervals along the user defined perimeter. A cutting process is implemented at a later stage that removes all bad data outside the perimeter that may be due to problem electronics or data processing.

6.2.3 Phase Correlation

The three-point fit described above established a geometric relationship or model between the two images being correlated. This model is used for two purposes. First, it predicts a search location, and second, it specifies a resampling from one frame to match the geometry of the other. Within a search area, the routine always correlates 32x32 windows from each frame. If the search area is larger, then one of the windows is moved in twelve pixel steps over the search area. The correlation is accomplished by taking the discrete Fourier transform in the complex domain, using the FFT algorithm, of each window. The low order row and column is deleted. The resulting matrices are multiplied element by element taking the conjugate of one element and dividing each result by its magnitude. This removes the power information yielding phase correlation. Then the inverse FFT is applied and the peak indicates the amount of shift of the sources. A final correlation is performed again at the peak to get a refined result, and a surface fit to the peak yields subpixel location accuracy. Good correlations are input to the model to reduce search.

6.3 Mosaic Procedures

6.3.1 MOS31

The MOS31 procedure has several functions. Firstly, it is designed to format all tiepoints used for the mosaic into the standard IBIS (Image Based Information System) file of 360 bytes. The mapped ground control points and edge matching points are merged in this operation. Secondly, preliminary editing is done at this stage based solely upon the correlation value obtained for the edge matching points. Generally, all points with correlation values greater than 140 were kept for later processing. No editing on the ground control points is done at this stage. Thirdly, a series of diagnostics is generated to aid in subsequent editing of the tiepoints. Generally, the gathering and the compilation of the tiepoints is an easy process when compared with the editing of the points. Editing is a labor intensive and detailed procedure.

A least squares fit is performed through the points at this stage in order to gather a feeling for the 'goodness' of the selected points. This helps isolate the very bad points immediately. A delta Z value (brightness) for each is also computed in order to ascertain radiance differences between scenes. On rare occurrences, a high correlation value may be returned from the phase correlation routine but is actually in error. A high delta Z value will help point this out early in the process.

6.3.2 MOS33

During this step, two operations are performed. While the ground control points are in reference to local line/sample and global line/sample, the edge matching points are in reference only to local line/sample. Local line/sample refers to the x, y coordinate position in the individual Landsat scenes. Formatting of tiepoints to fit VICAR convention requires that the points be referenced as new line/new sample; old line/old sample. Here, the edge matching points are mapped to the UTM's projection output grid based upon the

existing map control points (CPBLS) selected for each frame. In later steps, an offset is subtracted out to reduce computation time and then added back in later when the mosaic is pieced together.

Secondly, a listing is generated which maps the image edges to the output grid. This is helpful in determining image output size, since the rotation of the frame to north is taken into account. Table 5 shows the corner mapping of the edges of the constituent frames used.

TABLE 5

Corner Mapping

CORNER MAPPING - - CASE RGM900-PAT STEP 3

PAGE 1.001

FKAME	TO Line	TO SAMP	FROM LINE	FROM SAMP		LIN	LSQ FIT		SAMPLE	LSQ FIT
1111122222333334444455555666666	7890372166244421 1002881	8627859195375232083285038811328 53.006807649793328511744167266 17161595162289241388115951159516491314913844360414170485 186719231197649141384354485 1866333365236883374170485 186633336523688337445	100.00 2900.00 2900.00 100.00 100.00 100.00 2900.00 2900.00 2900.00 2900.00 2900.00 100.00 2900.00 2900.00 100.00 2900.00 100.00 2900.00 2900.00 100.00 2900.00	400.000 33.000.000 400.000 400.000 400.000 400.000 400.000 400.000 400.000 400.000 33.000.000 400.000 33.000.000 400.000 33.000.000 400.000 33.000.000 400.000 33.000.000 400.000	00000333331111111111111111111111111111	20366221 20366221 20366221 20366221 20366221 20366221 20366210 20366210 20366210 20366210 2036622 20366210 20366210 2036622 20366210 2036622 203662 2	222227777776666411111000000000000000000000000	-0.1985525529 -0.1988554666 -0.1988554666600 -0.19884226600 -0.222002244600 -0.1884422660 -0.188444400 -0.188554444400 -0.188554444400 -0.188554122555667718188 -0.116677128188188	0.985566511 0.98566511 0.998566577440 0.998566577440 0.998597797443 0.985779977443 0.9857799779994 0.985779977999999999999999999999999999999	0.66777000000888888666666666666666666666

This table predicts the size of the output picture and the location in the output picture of each of the four corners of the scene.

6.3.3 MOS34

The MOS34 procedure step performs two operations. The first operation subtracts an offset from the line/sample positions in the tiepoint file. The offset is subtracted from the 'To' line and samples in order to reduce the computation time and storage space. As an example, a given pixel may be directed to an address in the 5000 range in terms of image rasters. This would necessitate that the output image also be at least 5000 lines or samples large. In order to save time and space, an offset is subtracted out so that each frame can be adjusted within a small image domain rather than a large one. The large image domain is dealt with only after all corrections have been performed, and then for only a short time since the finished mosaic is divided into smaller, manageable quadrangles.

The second operation generates a diagnostic describing the interframe error or residual in pixels. This diagnostic depicts the difference in separately computed least squares fit for each frame, each point. The average for each point pair is then computed and stored as a 'To' location. Table 6 is the MOS34 listing output for UTM Zone 17 Phase II, Table 7 is the MOS34 listing output for Zone 18 Phase II, and Table 8 depicts the tiepoint's output in MOS34 for UTM Zone 17 second date.

MOS34 Output Listing UTM Zone 17

LANDSAT DIGITAL MUSAIL TIEPUINT DATA SET

PAGE 1.001

PENNSYLVANIA MUSAIC UTN ALME 1/ INITIAL MUSAIC DATA BASE

FRAME SEL TYPE	OFFSET	LINE	TO SAMP	FROM LINE	LASE FRUM Samp	76 2	FROM	INTERFR LINE	AME ERR SAMP	DELTA Z	T CONFIDENCE
AXXXXXXXXXXXXXX bissississississississississississississ	11000000000000000000000000000000000000	9823037576259265366523121361858824667766898360198498121564253884257678777401564253757611198776787787888999983601984987999999999999999999999999999999999	2223.00 2123.60 2027.71	28703295201527821091010099259011070089100900000000000000000000000000	1104000114820198000167945454555500000000000000000000000000000	35.0* 25.0* 25.0* 25.0* 14.2* 14.2* 24.0* 24.0* 25.0* 25.0* 25.0* 25.0* 25.0*	**************************************	00000000000000000000000000000000000000	0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0**	**************************************	1000 1000 1000 1000 1000 1000 1000 100

This tiepoint file is used as input to geometrically correct each Landsat scene used in the UTM Zone 17 mosaic.

PENNSYLVANIA MOSAIC UTM ADME 17 INITIAL MUSAIC DATA BASE

PAGE 1.002

FRAME S	IcPuint Eu Type	OFFSET	TO	SAME	FRCM LINE	LASE FRUM SAMP		FROM	INTERFF LINE	LAME ERF	DELTA	Z CONFIDENCE TO FROM
THILITIALITATIATIATIATIATIATIATIATIATIATIATIATIAT	MOVE MOVE MOVE MOVE MOVE	11100000000000000000000000000000000000	32445-00 32445-00 32445-00 32205-05 32205-06 31420 31420	76446523978497	1804.55 1804.54 1804.69 11671.629 11478.23 11478.33 11288.64 11280.18	142-4-4-4-4-4-4-4-4-4-4-4-4-4-4-4-4-4-4-	014539500253441941872202057169U735U0132425722204 	316479557445475390964036868782209067309053886404 2190807255774758852579917698617280346000491453 543484444344448333228329861728033428335000491453	055444mamamananalampaobeoneoneoneoneoneoneoneoneoneoneoneoneone	0352067898735800441053694192273811976470439470077 00011111111234677777420022110451344443101456565555	412140001211034351191834801623724651877638164211 0000000000000000005441221453102033110201107232	1000 10000 1

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LANDSAT DIGITAL MUSALO TIEPDINT DATA SET
PENNSYLVANIA MUSAIC UTM ZUNE LI INITIAL MOSAIC DATA BASE

FRAME SES TYPE	CFESET	LINE	TC SAMP	FR CM LINE	LASE FRUM SAMP	Ţ0 	FROM Z	INTERF	AME EPE	DE L TA	Z CONFIDENCE TO FROM
サンタンマンマンマンマンマンマンマンマンマンマンマンマンマンマンマンマンマンマン	11100000000000000000000000000000000000	11810736561066927542172597809953490245586924205596 118107365425156682167832033491454588908899 14810736577682510568216783203345066775592342685 148107665776886111111111111111111111111111111	96178558876609119959595072773026000051540751129539 966722399921268962279453129185991221062214745389 92468251601557848886569056315028128477222355304959842 22223344489772438556990563150888734374232053064959842 22223344488977688865666555455342343742320510876589842	446110044000000000000000000000000000000	######################################	NA457682000000000000000000000000000000000000	40m97-4000000000000000000000000000000000000	5577334916674127219067395542733312716578910327658	40757428864885684275670501415656421848501765428556666785238760075011069073275814093230585017654285	2794758000000000000000000000000000000000000	1000 1000 1000 1000 1000 1000 1000 100

PAGE 1.004

FRAME SET TYPE	CFFSET	LINE	TO SAMP	FRCM LINE	CASE FRUM SAMP	70	FROM	INTERFR	AME EFF	DELTA Z	Z CONFIDENC	E
	11000000000000000000000000000000000000	060317455638204635890496191549958963099246892 684221524394573731890496199154992 5309414460350000000000000000000000000000000000	0314822707913204208591529822125596087450520524522 5963145615873267147513575994225989900201487956744 5940451751357513575994225989900201487956744 5933120399866467861436405251172368583392163847664835 50331203998666514343621666501423345687654835 5033120399866651254678651666501423345687654835 50331203271412242222222222222222222222222222222	00000000000000000000000000000000000000		00000000000000000000000000000000000000	00000000000000000000000000000000000000	234852041.1.9940407762175432377020201207151228591	64804762076889968952325662135666251043429971531 441420414655435660011243449135666251043429971531	00000000000000000000000000000000000000	100 100 100 100 100 100 100 100 100 100	20060000000000000000000000000000000000

LANESAT DIGITAL MUSAIC TAEFDINT DATA SET PENNSYLVANIA MUSAIC UTM ZUNE LY INITIAL MUSAIC DATA BASE

FRAME	757 1 fr	1445	CFFSFT	LINE	SAMP	FPLM	CASE FRUM SAMP	7.0 	FROM 	INTERFRA	AME ERP SAMP	DE LTA	Z CONFIDENCE TO FROM
1 4 1 4 1 4 1 4 1 4	\$0.44\\$\\$\\$\\$\\$\\$\\$\\$\\$\\$\\$\\$\\$\\$\\$\\$\\$\\$\	A MARA WAN WAN WAN WAN WAN WAN A WAND	3700 400 3700 400	89504909466766523121361858882467766898360198496371 ************************************	930534623397753883196704674043227824488833500142764 82049049058581582789670467404359123591235903163106742764 876575184757333444274276527318537711867377737771257124673 957551847573332222111111111111111111111111111111	00000000000000000000000000000000000000		00000000019119805575780406090888320507243257164 000000000000191198055757804060904243257164 000000000000000000000000000000000000	000000006810073498668230565879251895949026145 0000000000041470521900325146227630998399569182190 44445843344448385338324822386345434	4126535002268765555555554444115443034623876656554	498232885413892085432095140047902485342284020352 004833165517655544444333221022233335773310000001 	000000000005101101149104220146211131212304104121 0000000000000000000000000000000	ORIGINAL PAGE 188 OF POOR QUALITY 110000000000000000000000000000000000

PENNSYLVANIA MOSAIC UTM ZUME 17 INITIAL MOSAIC DATA BASE

FRAME SEU TYPE	CFFS5T	LINE	TO SAMP	FFCM	CASE FROM SAMF	- <u></u>	FROM	INTERFR LINE	AME ERR SAMP	DELTA	Z CONFIDENC	М
THILLITILLITILLITIC CASSING CASSING COST CASSING CASSI	000 4000 4000 4000 4	90521857119985239569640300177990118129705248571305124695909099901177940524175555666768999677311671076864210864210864210864210864210868462946789273146642108642107405321178958899388888888887740532117827832828282828282828282828282828282828	952397849796785644627352444990541004990007 952594811150735424400485858555555555555555555555555555	0 890 00 991 091 111 1 285 8 9 367 7 9 63 8 13 2 0 7 2 7 8 6 7 9 7 2 5 5 7 8 7 9 6 3 6 1 7 1 8 8 8 1 1 1 1 1 1 1 1 1 1 1 1 1 1		5 0 4 5 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4 4	****** ****** ****** ****** ******	44444444444444444444444444444444444444	0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0**	4000I21103435I1************************************	100 100 100 100 100 100 100 100 100 100	. «««««««««««»» ««««««»»» «»» ««««««»» «»» «»» «» «

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ORIGINAL PAGE 19

PENNSYLVANIA MCSAIC UTM LUNE 17 INITIAL MCSAIC DATA BASE

FRAME SEL TYPE	PEFSET	LINE	SAMP	FROM LINE	LASE FRUM SAMP	- <u></u>	FROM	INTERFRA	ME EFF	DE LTA	Z CONFIDENCE TO FROM
######################################	3377000 40000000000000000000000000000000	24933732545890302224427077107694747190869752 1742942049752687757710769474719420476807688775771356148599877543144007798444174174111111	141517268224274407651942061547232441438144835444801 91580311797844735355913760691323050892590674400490 91580314785458509629421693101314534949018317451 26925924478529690183477400618660705789936918377451 1212223334545669012343444454576767878969018377451 222232222222222223333434445454576767878768760939313145313745313	161.00 442.00 352.00 265.00	\$\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	4287N144189NN80088055300000000000000000000000000000	098873847714650472511300000000000000000000000000000000000	78999843034849950U06144407089044492196791763459369	295184420203166116959845334933661811705852180830	670182203624325448160003000000000000000000000000000000000	ORIGINAL PAGE 18 OF POOR QUALITY OF POOR QUALITY 110000000000000000000000000000000000

LANDSAT DIGITAL MUSALU TIEPOINT DATA SET
FENNSYLVANIA MUSAIC UTM ZUNL 11 INITIAL MOSALU DATA BASE

FAAML SEU TYPE	CFFSFT	LINE LINE	T:: 5 AMP	FROM LINF	CASE FRUM SAMP	_Z_	FROM	INTERFA	RAME EPR SAMP	DELTA	Z CONFIDENCE
######################################	33700000000000000000000000000000000000	40494608937724253600055052974534645454545454545454545454545454545454	93748557090586046277379611104000140899286096386 9374855570905860462773796849604408992869623271 0395234772717174765001123413537133413111203099 7333233333333333333333333333333333333	51.3.00000000000000000000000000000000000	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	70072200020027027020000000000000000000	\$0.7500000000000000000000000000000000000	76251552745680573675789069906999063406099151292	19073863093014868508883653685208348063187364524U3 413328313421080	000000000000000000000000000000000000000	100 1000 1000 1000 1000 1000 1000 1000

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LANDSAT DIGITAL MUSALC TREPJINT DATA SET
PENNSYLVANIA MCSAIC UTH RUNE 17 INITIAL MOSAIC DATA BASE

FRAME SEM TYPE	OFFSET	LINE	TO SAMP	FROM LINE	LASE FREM SAMP	τ <u>ο</u> 2	FROM	INTERFAC	ME EFF	DELTA	Z CONFIDENCE
	40000000000000000000000000000000000000	10246648412084750046752187941280147480033221256 283606484120847501876014752187946088295114256 57-1-6-0-6-1-6-1-6-1-6-1-6-1-6-1-6-1-6-1-6	9U26862615681016502958777737197857266177599992034 68321762077953681698813842420934209388379367 52	00000000000000000000000000000000000000		00000000000000000000000000000000000000	00000000000000000000000000000000000000	10530 a36680 261218620680 089339 a353135748258756283	853702716074929947725468016536941922738119764704 210033232213002010215673552420022110451344443101	00000000000000000000000000000000000000	100 1000 1000 1000 1000 1000 1000 1000

PAGE 1.010

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FRAME SEE TYPE	CFFSET	LINE	TO SAMP	FROM LINE	CASE FRJM SAMP	<u> </u>	FROM	INTERFR LINE	AME ERR SAMP	DELTA Z	Z CONFIDENCE TC FROM
THILLITITITITITITITITITITITITITITITITITI	700 2990000 299000 299000 299000 299000 299000 299000 299000 299000 2990000 299	2575688219918488024556692754247668733223391459388679273397-3-4-59388679273397-3-4-59388676927542458320945568424-6-5-5-28046476396824-9-5-3-8-6-8-7-5-3-8-6-8-7-5-3-8-8-7-8-9-8-6-8-7-8-9-8-6-8-7-8-9-8-6-8-7-8-8-8-8-8-8-8-8-8-8-8-8-8-8-8-8	15512.25 15512.25 1534.11 1457.05 1352.20	55556500000000000000000000000000000000	11122111211111111111111111111111111111	538864044639716000000000000000000000000000000000000	25720004234506800000000000000000000000000000000000	001111111111110001005573319166741072190673955407333127165789	3947007740757428864865684275670501415656421848504565656565666785138760075011069073273814093230585	381642112794758000000000000000000000000000000000000	1000 11000 000 000 000 000 000 000 000

LANDSAT DIGITAL MUSAIC TIEPDINT DATA SET PENNSYLVANIA MCSAIC UTM ZUNE 17 INITIAL MOSAIC DATA HASE

FRAME SENT TIPE CFFSET LINE SAP FROM TO FROM INTERFRAME CERR DELTA Z CONFIDENCE LE SAME LE SAM		****			-		· AIN THIRE	-13 INII	TAL MOS	AIC DATA	HA SE		
Company Comp							CAS:	בָּ בַּ	FROM			DELTA	7 COMPTERM
3 3 2 FIX 100 2900 2550.22 1170.13 2217.05 120.00 0.0 1.0 1.0 100 100 100 100 100 100	53	マンツンマンマンシー アンコース アン・アン・アン・アン・アン・アン・アン・アン・アン・アン・アン・アン・アン・ア	70000000000000000000000000000000000000	889085596603174556382046351890496193860559446358890496193860510457014 559236268524394579733190496193865599386363 5792362685530243945797331904961938655993863 57923626855302439455745111111111111111111111111111111111	1985 989 1482 270 7913 2042 0859 1529 B1 22 23 24 3 4 3 4 3 4 3 4 3 4 3 4 3 4 3	00000000000000000000000000000000000000	10000000000000000000000000000000000000	00000000000000000000000000000000000000	,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,,	1032765923485204111994640776217543000000000000000000000000000000000000	0170008556680476837688996m95N385	00000000000000000000000000000000000000	OF POOR OULLE IN THE PART OF POOR OF POOR OF POOR OF POOR OF PART OF POOR OF P

LANCSAT DIGITAL MUSAIC TIEPDINT DATA SET PENNSYLVANIA MOSAIC UTM AUNE 17 INITIAL MOSAIC DATA BASE

FRAME SEG TYPE	CFFSFT	LINE	TC SAMP	FROM LINE	CASE FRUM Samp	<u>z</u>	FROM Z	INTERFR LINE	AME ERR	DELTA	Z CONFI	DENCE FROM
**************************************	29900 29900 29900 29900 2099000 209900 209900 209900 209900 209900 209900 209900 209900 2099000 209900 209900 209900 209900 209900 209900 209900 209900 2099	98087409785896368261341388858723542227455913 999642638520985442013418587873542227455913 15 26 26 26 26 26 26 26 26 26 26 26 26 26	1927322470951887545248542759789772117556554469115 77803355418327163193487541592567441 88136327163193487545253705610194848389267441 881363271654525371593555544444405360025474574574171574624171574644444440717157462433334564	5001909999010110000000000010010000000000	445.446 445.486 4225.846 4225.846 4225.846 4225.846 4225.866	*** 85983U59419247958U93U4 bl3381152U53&109429988U153 47221U4U477743U434700U970420U0907057570044UU7 22233333322232423223223224222222222222	**************************************	00040000000000000000000000000000000000	0.0**	**************************************		ORIGINAL PAGE IG OF POOR QUALITY 00000000000000000000000000000000000

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LANDSAT DIGITAL HUSAIL TIEPDINT DATA SET PENNSYLVANIA MCSAIC UTM LAME LI INITIAL MOSAIC DATA BASE

FRAME SET TYPE	PEFSET	TO LINE	TO SAMP	FROM	LASE FRUM . JAMP	<u></u>	FFOM Z	INTERFRA LINE	ME EPR SAMP	DELTA Z	Z CONFIDENCE
************************************	7000 2299000 000 77000 000 77000 000 77000 000	42294173740410226429749902288607359652494563136059 5148160371245825947124990228860735965011116896051 580.8712245820879479248. 209757024. 2097532087945580232222323233333333333333333333333333	125577137118285d2150590186d11827948277949311742998425395080144778801245679732444007533053779493117429455550060697732445679793440555432119874543218861212510372417412745743743211987454321886121251037246677794574374321198745432188612125103724667779459437432119874543218861212510372466777945943745743211987455432188612125103724666777945943745743211987455432188612125103724667779459437457457457457457457457457457457457457457	20000000000000000000000000000000000000	**************************************	7631676336201349209987274221817901571668970300000000000000000000000000000000000	762286734720146829908371131946148307542710000000 557799618377819J52897892239340617433655553400J00J0 2222323232223222322332332332322222222	87418520754321234567898777417632879351527575909:4	733265675517488531864583561579354983154814448157 ************************************	001120100101001000122004010189246946994750000000	100 100 100 100 100 100 100 100 100 100

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LANGSAT DIGITAL MUSALC TIEPDINT DATA SET
PENNSYLVAMIA MUSAIC UTM AUME 17 INITIAL MUSAIC DATA BASE

FRAME SEO TYPE	CFFSET	LINE	In SAMP	FROM LINE	CASE FRUM SAMP		FROM _Z_	INTERFR LINE	AME ERR SAMP	DELTA	4 CONFIDENCE
サール は、	299000 299000 229000 229000 2290000 229000 229000 229000 229000 229000 229000 229000 229000 2290000 229000	57607811554390190801127442715811775529263290949380707612508076125080764744279150807647474508076474745080764747450807647675	5561120549588184 69863709805835575299569368535263 006913437801421803513810989327802881748367845819 0405512747353009683145922727373301792379212944506124448830092 998977688666554747787871567243214801466124448830092 2222222222222222222222222222222222	00000000000000000000000000000000000000		10000000000000000000000000000000000000	000000000000000000000000000000000000000	9133994151 4484108000300000000000000000000000000000	273725974913466330114297163653899182742426460636 4358545442100001002220608253653899182742426460636	apaoapapapaoapaoapaoapaoapaoapaoapaoapa	1000 1000 1000 1000 1000 1000 1000 100

LANDSAT DIGITAL MUSAIC TIEPDINT DATA SET PENNSYLVANIA MUSAIC UTM ZENE LT INITIAL MOSAIC DATA BASE

FRAME SEU TYPE	CFFSFT	LINE	SAMP	FROM LINS	LASE FRUM SAMP	<u> 7</u> 6	FROM	INTERFR LINE	AME ERR	DE LTA	Z CONFIDENCE TO FROM
# 1	3260 2200 3206 2200	0006731188936463399842921895544074997154995996309 5144, 91489364682080461828201015 5344, 91489564074997154995680956309 5346, 9148968703 5346, 9148968703 5346	33747U86799017899916346449887001111221850608745052 42555453401026289956297021542528432942598990020168 4179250430107784073117800687331171720003550168 4555400804077840771800687331211720099990000000000000000000000000000	00000000000000000000000000000000000000		00000000000000000000000000000000000000	1000000006136600680300000000000000890798743011850 1000000099578868130000000000000000000000000000000000	4327247418855357913510378772188812377020120715	961684990223597141352990643482247135203347146242 	0000000128494827700000000000000000000000000000000000	ORIGINAL PAGE 18 OF POOR QUALITY 100000000000000000000000000000000000

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LANDSAT DIGITAL MUSALC TREPDINT DATA SET
PENNSYLVANIA MCSAIC UTH ZUME IT INITIAL MOSAIC DATA BASE

ERAME SEG TYPE	CFFSFT	LINE	JAMP	FROM LINE	FRUM SAMP	70 2	FROM Z	INTERFR	AME ERR SAMP	DELTA	& CONFIDENCE
######################################	00000000000000000000000000000000000000	787169789424994966390161819705249889724933732545890 787169789424294233476383871324933732545890 333550024530004554347121638838713274523933522478 3644406447706645481490640774417441744201111 110000000998875431097653219745866	05245229305346233995374360049000714151172682244274 79567448204995858192112441416578 8221797844473 11.3.4.3.3.3.4.4.5.5.8.3.2.4.4.16578 8221797844473 7666483695703714-1-2901-3-3-3-4-603704-3-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-	00000000000000000000000000000000000000	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	@0000000000000000000000000000000000000	00000000000000000000000000000000000000	12285914120535 0022317257441422253789998433548499	997-153-149823283541314566016948443295184420203166	00000000000000000000000000000000000000	1000 1000 1000 1000 1000 1000 1000 100

LANGSAT DIGITAL MUSALU TIEPOINT DATA SET
PENNSYLVANIA MOSAIC UTM ZUNE 1/ INITIAL MOSAIC DATA BASE

FRAME SEO TYPE	CFFSET	LINE	TC SAMP	ER OM LINE	FRUM Samp	₹G 	FR.OM 	INTERFRA LINE	ME ERR SAMP	. DELTA	Z CONFII	DENCE FROM
	00000000000000000000000000000000000000	30222427077107497471908649755442909900944604893722 26752088775070087471290849759442909900944604893722 21111102 *******************************	\$35591376069134305089459444801866157686444349 \$355913760691343050894590933485557090586 \$461845618660705745734513174751747676798989878993813711311213165484448877000 \$123456566667679898989481131111111111111111111111111111	08884991788664041685459553315445876545785785678578578546841	07707777777777777777777777777777777777	**************************************	1288 0578 00000000000000000000000000000000	500061449708904492196791763459369962515527456805 111120001000000010110010111101100000000	116959845333493340481811111111111111111111111111111111	4481600000000000000000000000000000000000	00000000000000000000000000000000000000	ORIGINAL PAGE IS OF POOR QUALITY 100000000000000000000000000000000000

LANDSAT DIGITAL MUSAIC TIERDINT DATA SET PENNSYLVANIA MOSAIC UTM ZUME LI INITIAL MOSAIC DATA BASE

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	TIEPUINT SEU TYPE		LINE	TO Samp	FF CM LINE	CASE FRUM SAMP	TO Z	FROM	INTERES LINE	RAME ERR SAMP	DE LTA	Z CONFIDENCE
NAMANAMANAMANAMANAMANAMANAMANAMANAMANAM	THE TANK OF THE TA	00000000000000000000000000000000000000	225536005560055600556005600560056005600560	740.62 602.26 664.01 624.75 883.76 662.98 363.51	2194.00 2078.00 2332.00	10014-000000000000000000000000000000000	02002222220200220002000200200200000000	20027002000000000000000000000000000000	736757896699066999996340609991512921353333568802612 2221111111131111222223340609915129213533356802612	485088365368520334806318736452403853702716074929 291975798780191992717635772644312210033243002	######################################	1000 1000 1000 1000 1000 1000 1000 100

PENNSYLVANIA MOSAIC UTM AUME 17 INITIAL MOSAIC DATA BASE

A - 44444444444444444444444444444444444	399 399 397 398 397 401 401 401 401	UNACCUM ACCOUNT ACCOUN	22000 3000 300	3045.00 3045.05 3045.75 2760.76 27733.354 3039.16 27333.875 21111.32 18428.08 15773.33	151.698587777373732 141.698587777373732 151.6983587777373732 155550424771.0330.32	283.00 2282.00 22857.00 22057.00 20079.00 20079.00 20079.00 20079.00 20079.00 20079.00 20079.00	LASE FROM DAMP 	T.Z. 0000000000000015	FROM	INTERFRA INTERFRA -0.86 -0.68 -0.68 -0.89 -1.89 -1.40 -1.40 -1.40 -1.40	94772540801673 0102156735521-7	DELTA 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0	100 100 100 100 100 100 100 100 100 100	NR 1110000000000000000000000000000000000
randinandan kananan dan kananan kanan kanana	1890123400789 DINE 450789 DIAGS		00000000000000000000000000000000000000	87-23-6097-85-89-63-68-2-613-4-13-88-85-87-23-67-98-8-13-5-86-38-85-82-98-8-4-2-07-4-13-88-88-87-23-67-98-8-13-5-8-8-8-13-5-8-8-8-8-8-8-8-8-8-8-8-8-8-8-8-8-8-8-	2.6709518875452485427597897721***********************************	20101000000000000000000000000000000000	14444444444444444444444444444444444444	3627526202793151584761148538595017 32147274*********************************	0594192479580930461338115205361094 0204797436434566095696266696557055	11102356655432025833680097678902460	1815057407148258753196964387358236 111723333334100123456677777778999009	30000000000000000000000000000000000000	10000000000000000000000000000000000000	10000000000000000000000000000000000000

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LANESAT DIGITAL MUSAIC TIEPOINT DATA SET
PENNSYLVANIA MUSAIC UTM ŁONE IZ INITIAL MUSAIC DATA BASE

FRAME SER TYPE	PERSET	LINE	T() SAMP	FROM LINE	CASE PRUM SAMP	70 2	FROM	INT EN FRA	ME EKP SAMP	DELTA	Z CONFIC	ENCE FROM
######################################	00000000000000000000000000000000000000	29745591342294417377404102226429745496533456764051 566791469-8-8-8-8-8-8-8-8-8-8-8-8-8-8-8-8-8-8-8	05446911512557713711828582150590184611829742514983892874151255771371188285821505901846611829742514992491335741110505050666497223618874915715959528088233334347576548321098747777486543210987459159595280333333333333333333333333333333333333	0809970919970018100298099990018100100100002246273501 048099709199700181001001000000000000000000		04.9** 23.2** 22.9** 26.1** 39.1** 37.6**	29988U1537631676336201349299872742218179***********************************	1405432468741852075432123456789877741763000000000000000000000000000000000000	0.0** 0.0** 0.0** 0.0**	2100000000112001010001220040101392************************************		

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OF POOR QUALITY

LANGSAT DIGITAL MUSALC TIEPDINT DATA SET PENNSYLVANIA MOSAIC UTM ZUNE LI INITIAL MOSAIC DATA BASE

FRAME SEW TYPE CFFSET	TO TI.	FROM FROM LINE SAMP	TO FROM	INTERFRAME ERR DELTA	Z CONFIDENCE TO FROM
22222222222222222222222222222222222222	\$341530549476095778879481940464454506486096049604670997968336147646709597998833614507899799883361450789979988376574799888889914527376624379978888888888888888888888888888888888	2133.960 2	**************************************	0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0	1000 1000 1000 1000 1000 1000 1000 100

FAGE 1.022

LANESAT DIGITAL MUSALU TREPGINT DATA SET PENNSYLVANIA MUSALU UTM ALME 17 INITIAL MUSALU DATA BASE

LASE FRAME SEE TYPE Τil FR_M LINE FROM Z Ţū FRUM INTERFRAME ERR LINE SAMP DELTA Z CONFIDENCE PEFSET LINE SAMP SAMP 1029.31 981.99 1012.70 2953-04 520.00 479.00 488.00 2460-00 0 6 2 7 1 4 4.9 4.9 6.8 9.89 -0.89 100 とり エソ・ロロ 0.0 Ü.Ö 31107-05 31107-05 2775-23 2874-71 28749-31 2949-47 0.0 Ĩŏŏ 2032.UU 2434.UU 2434.UU 0.0 0.0 100 Iõõ 1008.00 -0.50 J.0 8:8 950.00 4209.00 J . J 0.0 0.0 913.00 1052.00 1065.00 2011.00 4.0 0.0 10001000100010001000 U.2 01.0201.44341391 0.00 ĩũō J. Ü 0.0 100 2039.00 U.0 0000000 -0.3 -0.5 1238.00 4021.00 U. U 2713.61 2796.02 2755.83 2403.00 ĪŬÖ U.Ü -0.1 1165.00 0.0 100 J,Ö 0.0 100 0.0 ĩŏŏ 4534.JU J . Ū -0.4 īŏŏ 1376.00 4260.00 4267.00 4214.00 4.0 0.0 -U.3 100 0.0 1381.00 1481.00 145.00 1555.00 100 -0.5 0.0 8:8 ğ. 5 100 2902.00 0.0 U.U 0.0 ĪŬŬ 0.0 J.O -0,5 100 100 100 100 0.0 1658.00 1613.00 1748.00 100 2450.00 2430.00 2420.00 -0.3 -0.8 -0.7 **U.** 0 -4 1 -6 2 0.0 löö J . U -5.0259 J . U 1879.00 1902.00 1937.00 1929.00 2947.00 2947.00 ĪŌŌ U . U 0.0 -0.6 0.0 ĪŌŌ 100 3.0 U . U -0.3 100 0.0 لاء ف 0.0 Īõŭ 0.000 2492.00 0.0 īŏō 1975.00 1979.00 2051.00 1738.00 īčō -5-3-3-00 -3-3-00 -3-00 -3-00 -3-00 0.0 Ű.Ű 2600.18 2592.85 2757.41 0.0 3044.45 3143.60 Īöū 100 200000 3.0 4.0 100 0.0 100 £500.00 Jaŭ 2725.97 4044.00 2657.78 3158.78 3212.97 2989.97 2957.28 2910.56 U . U 2719-95 2719-95 2719-96 87129-678 224923-68 2843-98 2843-65 2928-65 2928-65 ذ. ب U.C 1690.00 2074.00 2073.00 2342.UU U.U J.0 -0.0 0.0 ĪÕÕ LOU 2410.00 J . () 0.0 6.1 0.0 100. 4.0 3.0 Ü.ö -6.2 -3.3 īöš 2090.00 0.00 40 LU-00 2096...0 1912..00 1851..00 1852..00 1952..00 2070..00 1979..00 2039..00 2039..00 2043..00 U a Ú 1.1 0.0 ĪŎÖ 100 2703.00 J.U 0.9 -0.5 0.0 ĪÕŌ ĨÕÕ 2895.00 J.U -0.0 0.0 100 IOU وأرمولاته JaÜ 0.6 3074.54 3223.36 3206.93 0.0 20/0.00 J.0 2871.00 2799.10 2817.24 3132.88 3186.37 1.2 0.0 ĪŪÖ 100 2059.00 J = Ü 0..0 -ō.5 0.0 100 27/5.00 u . Ú U.U 1.7 -0.5 -0.1 -3.4 3080.67 3222.05 100 J.Ü 3.0 0.0 3119.00 U.Ü 3279.05 2980.90 3213.39 0.0 ĪŪŌ יני כטוב 3.0 J.U -5.6 -4.7 3235.63 3016.66 3060.57 3311.59 3381.88 1.4 U . D 100 100 3171.00 J. J -0.3 100 0.0 100 0.0 1.9 -0.8 -0.5 2918.77 2876.74 2493.89 0.0 1035.00 **ビザガラッ** ひょ **U . Ü** 0.6 O. O 1774.JU 1497.JU IÖÖ コピヒコーリリ 1.0 0.0 -2.0 -5.6 U. 0 โจ้ง 3210.00

LANESAT DIGITAL MUSALU TIEFDINT DATA SET
PENNSYLVANIA MUSAIC UTM ZUNE 1/ INITIAL MOSAIC DATA BASE

FRAME SEN TYPE CEESET	LINE	TO SAMP	FA OM LINE	lase Frum Samp	Ţ0 	FROM	INTERFRA	ME ERF	DELTA	Z CONFIDENCE TC FROM
22200000000000000000000000000000000000	904825788925356278979d378714949254460756478888857724460791455498157448813783448813742209980554481114889053350004	9200422374372917467 U2908844911886291779482779493 865765191355694156543819151405971698875530537767 01231559083752448767485774688115520724157169 90674638315597416516448577477688115520724157169 333443456655456654737768864455545013706902762 3334333333333333333333333333333333333	00000000000000000000000000000000000000		0,000000000000000000000000000000000000	00000000000000000000000000000000000000	812883413747607389928049791211053976828793515575	3481686343517304176579176049637111179454683154814 ***********************************	000000000000000000000000000000000000000	100 1000 1000 1000 1000 1000 1000 1000

LANDSAT DIGITAL MUSALC TIEPDINT DATA SET PENNSYLVANIA MCSAIC UTh LUNE 17 INITIAL MCSAIC DATA BASE

PAGE 1.024

FRAME S	Titholpi	CFESET	LINE	TC SAMP	FRCM LINE	Lase Frum Samp	70	FROM	INTERFR	AME ERR SAMP	DELTA	Z CONFIDE	ENCE FROM
A DA	世紀の世紀の世紀の世紀の世紀の世紀の世紀の世紀の世紀の世紀の世紀の世紀の世紀の世	00000000000000000000000000000000000000	8960058577600781339019079442711581123702439091927784420350545125058890190784420350585901907844203505859019078442035058590190788590190784444088512370288662748088768877444408866364037772888675456877445687745527105800364033777181388675468774552710580036403377718138867546877474888677488867748886774888877488887748888774888877488888774888887748888877488888774888888	1174295561120549588184498637098058355752299569368 44748640069112054958818449863709805835575752899569368 93557404470889351966447275	#830991-179-0000000000000000000000000000000		029002000000000000000000000000000000000	00000000000000000000000000000000000000	75909291339941512434108003029894675176020727564 01010222222222222222222222222222222222	148157273725974913466330114297163653899182742426 544645435354544210UUULUOQUOQUOQUOQUOQUOQUOQUOQUOQUOQUOQUOQUOQU	02	100 100 100 100 100 100 100 100 100 100	

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LANDSAT DIGITAL MUSALC TIERDINT DATA SET PENNSYLVANIA MUSAIC UTM ZENE 17 INITIAL MUSAIC DATA BASE

FRAME SEL TYPE	OFFSET	LINE	SAMP	FRCM	Case Frûm Samp	Ţ0	FROM	INTERFRA LINE	ME ERR SAMP	DELTA	Z CONFIDENCE TO FROM
	00000000000000000000000000000000000000	93800580067318880022188	535263337470868348181850847022206557333099887862625878 536.5.19425544483850847022206557333099887862625878 838007324179255.448389400861556447903871626625878 838007324479255.44412675746144128833114337293422333 111111111111111111111111111111111	00000000000000000000000000000000000000		00000000000000000000000000000000000000	**************************************	45670448N784740000000000000000000000978588987660584	0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0**	00000000000000000000000000000000000000	100 100 100 100 100 100 100 100 100 100

PAGE 1.026

											DA DE		
FR	EME	SEU TYP	E OFFSET	<u> LINE</u>	TO SAMP	FROM	CASE FRUM SAMP	<u> 70</u>	FROM	INTERF	RAME EKR SAMP	DELTA	Z CONFIDENCE
55355555	0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	MINUTE MI	9900000 9900000 9900000 9900000 9900000 9900000 9900000 9900000 990000 990000 990000 990000 990000 990000 990000 990000 99000000	597334420193393088055724481226053733333333333333333333333333333333333	2007 - 17 20057 - 37 20057 - 37 20057 - 73 20057 - 73 2	\$1000000000000000000000000000000000000	\$\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	70/16888HG0007G000000000000000000000000000000	64490042500000000000000000000000000000000	059021653564314526378379397408538522633491807944 32141100400010101011110000110121000001100122222	1974321031144567756667877556676443110100221879991	75.85.1.67.0.0.0.0.0.0.0.0.0.0.0.0.0.0.0.0.0.0.	1000 1000 1000 1000 1000 1000 1000 100

LANDSAT DIGITAL MUSALO TIEPDINT DATA SET PENNSYLVANIA MOSAIC UTM ZUNE 1/ INITIAL MOSAIC DATA BASE

FRAME SET TYPE	DFFSET	LINE	TC SAMP	FROM LINE	EASE FRUM SAMP	- <u></u> -	FRGM Z	INTERFRA LINE	AME ERR SAME	DECTA Z	Z CONFIDENCE TO FROM
	00000000000000000000000000000000000000	117682379936463398642921661845695438465565365870230814657936487923081465695487923081465699465793686531984923081465969948372933333333333333333333333333333333333	03203037799017899991634644988706111195778/948919833 02137487799017899991634328164514697775239 0541373010997649562970215425284328164697775239 119991330998077649581939939177035177109434***********************************	00000000000000000000000000000000000000	00000000000000000000000000000000000000	00000000000000000000000000000000000000	0000000005941667409800000000000000000000000000000000000	888098551885535791351037877218881775641032355103 23310112100100001110010001101110101111000000	10892241022m597141352990643482247215228364385357	00000000128494327700000000000000000000000000000000000	ORIGINAL FACE EX OF POOR QUALITY

PENNSYLVANIA MOSAIC UTH LUNE 17 INITIAL MOSAIC DATA BASE

FRAME SED TYPE	CFFSET	LINE	TO SAMP	EROM	CASE FRUM SAMP	70 2	FROM Z	INTERFRAME LINE S	ERR DELTA	Z CONFIDENCE TO FROM
######################################	46000 46	4127323835435486009711491888855556653891772195649945 439675-1210384-195564845189129139033649945 43110035113637-6-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-	319404648495648608 08444559839107123880019224883179982509182532512532477451258255629118772769712565131253247745455629118772767745125562534455543384343211122231	100.5500 -500.5500 -		#3####3N#030000000000000000000000000000	8\87\59\400000000000000000000000000000000000		185500188853036467324498039662214434139112132556	100 1000 1000 1000 1000 1000 1000 1000

70

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PENNSYLVANIA MESAIC UTM ZUNE IZ INITIAL MOSAIC DATA BASE

ERAM	ME SEA	PGINT	PERSET	LINE	E T J	FRUM LINE	CASE FRUM SAMP	TO	FRCM	INTERFR LINE	AME ERR SAMP	DELTA Z	Z CONFIDEN	CE CM
000000000000000000000000000000000000000	44444444444444444444444444444444444444	CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC	3500 4600 3500 4600 3500 4600 3500 4600 3500 4600 3500 4600 3500 4600	450761877463756697749290482578898888577987878787878787878787878888878786081887854588888577244608478254518888857724460847825454588888577244460847845454545888888577244460847854588888888888888888888888888888888	192.80 357.41 319.95	00000000000000000000000000000000000000		202200220022002200220022002200220000000	97070000000000000000000000000000000000	353016192622217439943812883413747637389928049791 	363002m500m5514678626m46168634351730417657917604 481286300000000057876065787613520112m30112m3200124586	000000000000000000000000000000000000000	100 1 100 1 100 1 100 1 100 1 100 1 100 1	RIGINAL PAGE IG F POOR QUALITY

LANDSAT DIGITAL MUSAIC TIEPCINT DATA SET PENNSYLVANIA MCSAIC UTM ZONE LY INITIAL MOSAIC DATA BASE

FAGE 1.030

						-		·	•	· ·		
FRAME SE	EPUINT U TYPE	OFFSET	LINE	TO SAMP	FR GM LINE	CASE FRUM SAMP	, Z	FROM Z	INTERF	AME EPP SAMP	DE LTA	Z CONFIDENCE TC FRGM
11111111111111111111111111111111111111	は、	600 4600 600 4600 600 4600 600 4600 600 4600	25080135600085810034820501659474645973384201939308J4146561001. 36801176681176817821793968945245260580031456101. 5488814488241812440764000581782575257947800288436101. 548885638233 11111222223345555555554444 1 2221 122121.	911 886 6 9 1 7 7 3 3 0 9 9 8 5 7 1 6 2 6 2 6 2 6 9 1 7 7 6 9 6 9 1 7 7 8 6 1 8 7 1 6 2 6 2 6 2 6 2 6 9 1 7 7 8 6 1 8 7 1 6 2 6 2 6 2 6 2 6 9 1 7 7 8 6 1 7 7 8 6 1 7 7 8 6 1 7 7 8 6 1 7 7 8 6 1 7 7 8 6 1 7 7 8 6 1 7 7 8 6 1 7 7 8 6 1 7 7 8 6 1 7 7 8 6 1 7 7 8 6 1 7 7 8 6 1 7 7 8 7 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	00000000000000000000000000000000000000	714-2-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1	100000000050615329924959764490042500000000000000000000000000000000	0000000078720851825630370216333100000000000000000000000000000000	211U53976897352292766063405902165356431452637837	9637111179481746692498922609776665993363577337525 7809988850667776654560333397432123	000000000000000000000000000000000000000	1000 1000 1000 1000 1000 1000 1000 100

LANCSAT DIGITAL MUSALU TIEPUINT DATA SET
PENNSYLVANIA MOSAIC UTM ZUNE IZ INITIAL MOSAIC DATA BASE

FRAME SE	TEF YINT	OFFSET	LINE	SAMP	FROM LINE	LAS C FRUM SAMP	<u> 70</u>	FROM	INTERFRA	AME ERF	DELTA Z	Z CONFIL	DENCE FROM
14444000000000000000000000000000000000	THE PROPERTY OF THE PROPERTY O	46000000000000000000000000000000000000	73724481226057733770577 044793107682377057244812250053733770577 044793107682377098747277773331112312346443955255557494522492449222432234321792525555749454249222322324039175222232403244455555555555555555555555555	77300361965778735002837330320363765195959542520849 734708864965778735002837330320363765195959542520849 755138639463577543356234497231343415054754335603657211441131314161914774747474747474747474747474747474747	00000000000000000000000000000000000000			OOOOOOOOOOOOOOOOOOOOOOOOOOOooooooooooo	93974085386NN6384918DF9448888985985000000000000000000000000000	0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0***	00000000000000000000000000000000000000	10000000000000000000000000000000000000	ORIGINAL PAGE IS OF POOR QUALITY 3200000000000000000000000000000000000

PAGE 1.032

PENNSYLVANIA MOSAIC UTM ZUNE 17 INITIAL MOSAIC DATA HASE

FRAME			TG LINE	SAMP	FROM	LASE FRUM SAMP	- <u></u> -	FROM	INTERFRA	AME ERR SAMP	DELTA	Z CONFI	DENCE FRCM
0 0	23 fix 24 fix 25 fix	3000 4600 3000 4600 3000 4600	517.64 670.06 1110.86	932.94 1950.73 2124.97	380.42 370.22 664.98	4/7.29 1201.71 1742.09	30.4** 25.1** 32.9**	****	0.0 0.0	0.0**	******	100 100 100	100 100 100

MOS34 Output Listing UTM Zone 18

LANDSAT DIGITAL MUSAIC TIEPGINT DATA SET PENNSYLVANIA MCSAIC UTM ZUNE 18 INITIAL MCSAIC DATA BASE

PAGE 1.001

FRAME		TYPE	CFFSET	TO	SAMP	FROM	FRUM SAMP	_ <u>Z</u> _	FROM	INTERFRA LINE	ME ERR SAMP	DELTA Z		PROM
AND	345 0 8 95 6 7 6 4 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1 1	TANDANAMANAMANAMANAMANAMANAMANAMANAHAHAHAHAH	1000 6100 11000 6100	246 #3333371442938883777145188351178607156618857743379 271165146281774782178217866778218666778218666774715679273879 2711766792383878787878787878787878787878787878787	575545 010121550416018594791487388662 0098411688125 •692274649853339972547290238884616519127794226360 800000000000000000000000000000000000	103.13.45402.57458.0844708.46658095000000000000000000000000000000000	00000000000000000000000000000000000000	201-1681-17-688 	**************************************	00000000000000000000000000000000000000	00000000000000000000000000000000000000	**************************************	111111111111111111111111111111111111111	

This tiepoint file is used as input to geometrically correct each Landsat scene used in the UTM Zone 18 mosaic.

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LANDSAT DIGITAL MUSALC TEPPCINT DATA SET
PENNSYLVANIA MUSAIC UTM ZURE 18 INITIAL MUSAIC DATA BASE

FRAME SEZ	JINT TYPE OFFSET	LINE	SAMP	FROM LINE	CASE FROM SAMP	T G Z	FROM	INTERFRA LINE	ME ERR SAMP	DELTA	Z CONFIDENCE TO FROM
9-7-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-	000 000	44674403868590443716611094859709548180481647732000244885904027849486879987782888900011112221840680405566780111122468893181622223333333333333333333333333333333	930760590422444134035654586877002629612675066619511805941 93076059042200552976888980070701977770321279241372 83344-8-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1	00000000000000000000000000000000000000		00000000000000000000000000000000000000	00000000000000000000000000000000000000	232248318429506125234915119077330935395415128010	531418377247696382976825440318640157456098895774 678775566764421101000222597090166640157456098895774	00000000000000000000000000000000000000	1000 1000 1000 1000 1000 1000 1000 100

76

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LANDSAT DIGITAL MUSAIC TIEPCINT DATA SET PENNSYLVANIA MUSAIC UTM ZOME 18 INITIAL MUSAIC DATA BASE

FRAME SEL TYPE	CFFSET	LINE	SAMP	FRCM	CASE FROM SAMP	, <u>, , , , , , , , , , , , , , , , , , </u>	FRCM	INTERFRA	ME ERP	DFLTA Z	Z CONFIDENCE TO FROM
	1000 61000 1000 61000	31059U7602454559494165119066888373116133637448 39291916679615177817765119065898373116133637648 47137440952762762765188653466888877658321962109865546688887902109235566666677 2222222222222222111111	79565368159711879179305424405742578239766490 33203 8805753966120004169862998575547392229616459402303 9381399466120004169862998575547392229616455402303 75207435592703890199544232742035350207733722211111111111111111111111111111	000000828344724545399437556000000000000000029242737955560000000000000000000000000000000000	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	27364580191567726199134420000000000000000000273337169 17864173746717658617377888400000000000000000000000000000000	9121573765049870117891911000000000000000680963778 0841900564750982098889600114900000000000000504054763 222222222222222222222222222222222222	4750%95895584045885404558888044407868558880454888880444078685588804548888880444078685588804548888888	155444404334349461833341174839809100087545587602 190000011000011000000000100101111001701 11-11-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1	7495=25756994408408888579000000000000000083474481	100 1000 1000 1000 1000 1000 1000 1000

PAGE 1.004

PENNSYLVANIA	MOSAIC	UTm	Zamě la	INITIAL MUSAIC	
+	~		~	Trurithe Wrighto	DATA BASE

										-			
FKAN	T SEU	TYPE	CFFSET	LINE	TO SAMP	FR OM LINE	CASE FROM SAMP	<u> </u>	FROM Z	INTERF	RAME ERP	DE LTA	Z CONFIDENCE TC FROM
^^^^^^^^^^^^	TATA TATA TATA TO SO OF THE SOURCE OF THE SO	CCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCCC	41000000000000000000000000000000000000	427.40	77991080150018594771487388562609841108123667902244 21119139139139139139139139139139139139139	369960000000000000000000000000000000000		55745065820615329924594490U425U000U000U000U00U00U00U00U00U00U00U00U00	374313593687208518253002163331000000000000000000000000000000	4118290±0711966461908781131650334870017123224831 11000112411002111110223244131650334870017123224831	632601052496254814985641909084372236922253141837 11101010375677776654503084422041114474	28314316568104532901826786291600000000000000000000000000000000000	100 100 100 100 100 100 100 100

LANDSAT DIGITAL MUSAIC TIEPGINT CATA SET
PENNSYLVANIA MUSAIC UTM ANNE TO INITIAL MUSAIC DATA BASE

FRA	ME SE	PULNI	OFFSET	LINE	SARP	FROM LINE	CASE FRUM SAMP	_ <u>z</u>	FROM	INTERFR LINE	AME ERR SAMP	DELTA	Z CONFIDENCE TO FROM
000000000000000000000000000000000000000	11414141414141414141414141414141414141	A A A A X X X X X X X X X X X X X X X X	00000000000000000000000000000000000000	859 U437166110948597499546183443914U7002669946536424733954618374690028715940500287159405002871570607774305049600777488674719163662424244202144020367769631779563179566357724518402421345366357769635776963577788867676977788867477563177956635772453662137866357769635777888674789676769777888674777888671779567676769769777888671779567675769769777788867177956777956776977788867777888677778886777797563177956777956776977788867777888677779756777956777788867777977888677779756777975677778886777797778886777797567779756777788867777977788867777975677797567777888677779777888677779756777778886777797778886777797779779779797979	4134035654587702629612675788498950327615774719526 10052676839800707619278787881572667016321 100526763173300767878899503224434572790 88832472577969667336656667888585715827551034572111 888324324222333333333333333333333333333	00000000000000000000000000000000000000		00000000000000000000000000000000000000	OOOOOOOOOOOOOOOOOOO	8429606125234491511907~330000000000000000000000000000000000	0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0***	00000000000000000000000000000000000000	1000 1000 1000 1000 1000 1000 1000 100

PENHSYLVANIA MCSAIC UTM ZUNE 16 INITIAL MOSAIC DATA BASE

FRAME SEQ TYPE	OFFSCT	TINE TO	SAMP	FROM LINE	LASE FROM SAMP	70 	FROM	INTERFR LINE	AME ERR SAMP	DELTA	Z CONFID	ENCE FRCM
######################################	00000000000000000000000000000000000000	3041.05 3154.36 2684.45 2881.73	2778.46 2778.46 2760.56 2750.56 2703.92 2588.45	00000000000000000000000000000000000000		936640599063327552654905181303129000000000000000000000000000000000	31247952677980472450940634791247000000000000000000000000000000000000	983811098001663268300318730412441725836673323543 	583358397441330839393677829443423131099667734751 	624171064384523949165509844481759000000000000000000000000000000000000	000300000000000000000000000000000000000	ORIGINAL PACE IS OF POOR QUALITY 00000000000000000000000000000000000

LANCSAT DIGITAL MUSAIC TIEPDINT DATA SET
PENNSYLVANIA MOSAIC UTM ZLME 10 INITIAL MOSAIC DATA BASE

FRAME	T LEP	INT TYP.c	GFFSET	LINE	SAMP	FROM	HASE FRUM SAMP	70 2	FROM	INTERFRA LINE	ME ERR	DE LTA	Z CONFIDENCE TO FROM
97777777777777777777777777777777777777	AND AREA PHATTER AND AREA CONTROL AT A CONTROL AND AREA C	**************************************	3-00 53C0 1100 83300 1100 83300	708416484773105990760244545519965519065142058 2054************************************	206661951180592179565368159711879479305424405742 876082127924137288057396612000416936299857554339 5088648292909836293311594233393121075974200364233931471 508864829230159433317533915927034023392139 5913544333221159999986521 1122224555566677722203139 1211111111111111111111111111111111111	0130831107788334857129000000000000000000000000000000000000	07770000000000000000000000000000000000	03534730012589229121573765049870117891911000000000000000000000000000	0441368795239536273645801915677261991344200000000000000000000000000000000000	693539541522801047507395895581015885104550230114 0614110000003000014111111111111111111111	015745609889577415544440433494946183334117483980 4400000100000100000011177711107000000000	0102125306028596749512575699410840888857900000000000000000000000000000000	ORIGINAL PAGE IS OF POOR QUALITY 1000 1000 1000 1000 1000 1000 1000 10

LANUSAT DIGITAL MUSAIC TIEPDINT DATA SET
PENNSYLVANIA MCSAIC UTM ALME LE INITIAL MOSAIC DATA BASE

EHAME	I I E P	TAPE	GFFSET	LINE	TC SAMP	FROM	CASE FRUM SAMP	70 2	FROM	INTERFR	AME ERF SAMP	DELTA	Z CONFII	PENCE	
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LANDSAT DIGITAL MUSALO TIEPDINT DATA SET
PENNSYLVANIA MOSAIC UTM LUNG 18 INITIAL MOSAIC DATA BASE

FRAME SON TYPE CEES		TC. SAMP	FROM	LASE PRUM SAMP	- <u></u> -	FROM Z	INTERFRA LINE	ME EPR SAMP	DELTA	Z CONFIDENCE TO FROM
83333333333333333333333333333333333333	00 30319-9442-1933019-944-2-933019-9-9-9-9-9-9-9-9-9-9-9-9-9-9-9-9-9-9-	2631357096684979610296404251423099871657438861 56969078463099929840370351086080275042323321849 5765783765764737504232332186080275042323321849 5765783775049373327035108608027520453 5765783750477327049373873737504752075349435 576783775049373873734943 5767837353734943 57678373555554443332218 57678577520998775208533333333333333333333333333333333333	00000000000000000000000000000000000000	100 100 100 100 100 100 100 100 100 100	345608498182345988298033550653463284655668203 	307834756083715740953979796088001974879633561758 46611773616171606852321708626613333070111392588452	577690893496356734377318089544524345343433621435 0000010010010010000000000000000000000	458964951425945913342186233549850442220210223231 	048874742109539218355165810456641582190022207556 8240031855192120458863630288967508514444344332333 4666566165662655544444455334444444444443323333	0 1000 1000 1000 1000 1000 1000 1000 1

LANDSAT DIGITAL HESAIC TIEPGINT DATA SET
PENNSYLVANIA MCSAIC UTM LUNG 18 INITIAL MDSAIC DATA BASE

FRAME	Tiel Séa	Type	<u>DF#SET</u>	TO LINE	TC SAMP	FRUM LINA	lase Früm Samp	. <u>to</u>	FROM Z	INTERFR. LINE	AME ERF	DELTA Z		ENCE FROM	
19997 X 99 X 99 Y 99 Y 99 99 99 99 Y 2000 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0 0	07 05-07 001-12-47 07 89 01-12-39 04-51 - 445 07 89 01-12-4-67 80 9-69-1-25 05 05 05 05 05 05 05 05 05 05 05 05 05	AND XXXX XXXX XXXX XXXX XXXX XXXX XXX XXX	1100 83000 11100 8300 11100 8300 11100 8300 11100 8300 11100 8300 11100 8300 1	9304911199044578 96982321999044578 9698232199904299863231194843768525469157922887 937049650473062002851173377492351982155702465481 8900176504306396396396938024691355702466548128 8900176531198764310876431087643110876431108764311087643193332	0005344495965980206158488609564903320377910861501953453449555155155155155155155155155155155155155	0000069755414408476070568000000000000000573170581 735555555844447607056800000000000005573170581 73555555555555555555553752355314 1356555555555555555555555555555555555		302548633080466440343518995809637183743135936551 080141810014351300446514513135936551 08014181001435137750564623108986 090148101501450145000000000000000000000000	045564983400155443715883062733371695574566582032 337604645681826991555557651413029942880084448420731151555416445555555555451413020	970270807310422033687733020820156234118290107080	092658185776136021359977135455876026326010524053	767083750680311107638735936834744812831431656581 6485371258920719131314888116882441577907846555991 3411415543155355555543564626666611111523116646569	11000000000000000000000000000000000000	000000000000000000000000000000000000000	ORIGINAL PAGE IS

LANUSAT DIGITAL MUSAIC TIEPDINT DATA SET
PENNSYLVANIA MOSAIC UTM LUNE 18 INITIAL MOSAIC DATA BASE

FRAME	TICHOLNI SEU TYPE	OFFSET	LINE	SAMP	FRCM LINE	FRUM SAMP		FROM Z	INTERFF LINE	RAME ERR SAMP	DELTA Z	Z CONFIDE	NCE
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PENNSYLVANIA MOSAIC UTM ZONE 20 INITIAL MOSAIC DATA BASE

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FRAME	PEN TAN	CFFSF	LINE	SAMP	FRCM LINE	LASE FRUM SAMP	<u>7</u> 0	FROM	Intek fi Line	IAME ERR SAMP	DELTA Ž	Z CONFIDENCE
808 0888 0888 0888 0 088	NOW YOU WIND THE CONTROL OF THE CONT	773000 773000 773000 773000 773000 773000 773000 773000 77330000 7733000 7733000 7733000 7733000 7733000 7733000 7733000 7733000 7733000 7733000 7733000 7733000 7733000 7733000 7733000 77330000 773300 773300 7730		502119228915053168869422480926313570966844333706 468236249915653503972263438256969078463032708 8855864	182.67 182.88 182.34 182.34 181.64 1281.82	174740000000000000000000000000000000000	944.3 95.7 95.7 91.8 41.3	**** ****	4368890948942235426213214577690893496350220000000000000000000000000000000000	5102816872274401049238970554589649514259400000000000000000000000000000000000	***** ***** *****	00000000000000000000000000000000000000

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LANESAT DIGITAL MUSAIC TIEPOINT DATA SET PENNSYLVANIA MUSAIC UTM ZUME 16 INITIAL MOSAIC DATA BASE

FRAME SES	TYPE C	FFSET	LINE	TC SAMP	FRCM	CASE FROM SAMP	7 D	FROM	INTERFR.	AME ERF	DELTA	Z CONFID	ENCE FROM
9-13-15-27-3-1223-45-45-27-35-36-45-76-37-37-37-37-37-37-37-37-37-37-37-37-37-	WHANAWAY WAN WAN BANKA WAN WAN WAN WAN WAN WAN WAN WAN WAN WA	73000 733000	788-42	71559746544859453435731152812548111.6511919438204 3147813251717510873784278919023113259941939560577 21023675035338234349294772763517027635478888 7276887503533812384062917406284787947114.6.6.6.6.6.6.6.6.6.6.6.6.6.6.6.6.6.6.	2260719922001010000000000000001114552129300000000000000000000000000000000000		20 * 4* 21 * 88 * 20 * 08 * 20 * 08 * 20 * 08 * 20 * 08 * 21 * 08 * 21 * 08 * 21 * 08 * 22 * 08 * 23 * 08 * 24 * 08 * 25 * 08 * 26 * 08 * 27 * 08 * 28 * 08 * 29 * 08 * 20 * 20 * 08 * 20 * 20 * 08 * 20 * 20 * 08 * 20 * 08 * 20 * 08 * 20 *	**************************************	00000000000000000000000000000000000000	0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0**	**************************************	00000000000000000000000000000000000000	999999999999999999999999999999999999999

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LANCSAT DIGITAL MUSALU TIEPOINT DATA SET

PENNSYLVAVIA	MOSATO	UTM	AUNE 18	INITIAL	MOCATO	DATA
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FRAME	Tickolki Sau Tybe	OFFSET	LINE	SAMP	FROM	LASE FRUM SAMP	- <u></u> -	FP QM	INTERFR LINE	AME EFR	DELTA Z	Z CONFIDENCE TO FROM
10000000000000777777777777777777777777	Mubility a laboral case and a sign of a case and a case	3500 7300 3500 7300 1500 10200 1000 10200	3902542910802266202915769168431784522 356308029159250221274482830706184212 23228623010102276728557767359269668279 32328623010122767955786557767268627926968279 323231012336744485555566666789787878787898785557867878787898787898787898787898787898787898787898787898787898787898787898787898787898787898787898787898787898789878789878789878789878789878789878789878789878789878789878789878987878987878987878987878987889878878	8 48 9 1 2 3 3 9 7 9 6 1 0 2 9 6 4 0 2 7 5 7 8 1 9 2 9 8 4 0 3 7 5 7 8 1 9 2 9 8 4 0 3 7 5 7 8 1 9 2 9 8 4 0 3 7 5 7 8 1 9 2 9 8 4 0 3 7 5 7 8 1 9 2 9 8 4 0 3 7 5 7 8 1 9 2 9 8 4 0 3 7 5 7 8 1 9 2 9 8 4 0 3 7 5 7 8 1 9 2 9 8 4 9 8 2 2 1 1 2 1 2 1 2 1 2 2 1 2 2 1 2 2 1 2 2 1 2 2 1 2	00000000000000000000000000000000000000	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	000000000000000005740953979796088001974879638561758 000000000000000000000000000000000000	00000000000000000000000000000000000000	0879025011409867343773180855445243453454533021435	16257807288515591834218428549850442220210228231 99899018254109200122211100010000000000000000000000	00000000000000000000000000000000000000	1000 000 000 000 000 000 000 000 000 00

LANDSAT DIGITAL MUSAIC TREPGINT DATA SET
PENNSYLVANIA MOSAIC UTM AUNC 16 INITIAL MOSAIC DATA BASE

FRAME SES TYPE	<u>OFFSET</u>	LINE	TC SAMP	FROM LINE	CASE FRUM SAMP	Ť0	FROM	INTERFRA LINE	ME ERR SAMF	DE LTA		CENCÉ FROM
TTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTTT	000 10200 000 10200	100 0.25 932.19 973.39 265 0.40	2200.37 2629.84 2370.57 1142.57 182.04 273.71 375.56	00-67-60-00-00-00-00-00-00-00-00-00-00-00-00-	12430.00000000000000000000000000000000000	554437158 ************************************		\$702*080*********************************	0.0*** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0**	76708375068031111076387***********************************	1000 1000 1000 1000 1000 1000 1000 100	ORIGINAL PAGE 16 OF POOR QUALITY 00000000000000000000000000000000000

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LANDSAT DIGITAL MOSALE TIZPEINT DATA SET PENNSYLVANIA MESALE UTM LEVE TO INITIAL MOSALE DATA BASE

FRAME	TEPOINT	CFFSET	LINE	SAMP	FROM	that frui anmr	10	FROM	INT CREA LINE	AME EFR SAMP	DE LTA	2 CONFID	FNCE FROM
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LANGSAT DIGITAL MUSAIC TIEPGINT DATA SET PENNSYLVANIA MOSAIC UTM ANNE LO INITIAL MOSAIC DATA DASE

FRAME SET TYPE	CFFSET	LINE	SAME	FROM	LASE FRUIT SAMP	70	FROM	INTERFFA	ME ERE SAMP	DELTA	Z CONFICENCE FROM
100 001 101 101 101 101 101 101 101 101	100 10200 11000 10200	029985-7-11480 45267-3-3-3-11480 45267-3-3-3-11480 45267-3-11480 45267-3-11480 45267-3-11480 45267-3-11480 45267-3-11480 45267-3-11480 4527-3-11480	1738860954534357311528122548111651149194382704310494 179853621087378427189231312165214319438231412336673784247197183251601725 23361123667947173124794911617273193124673101725 43217667733221111111111111111111111111111	00000000000000000000000000000000000000		49-08-0605-39-NND-04-8-NNN-449-37-8-NON-000-3000-3000-3000-3000-3000-3000-3	94-1-1-189953U-337-31-99-1-67-1-9847-30U-6-6-0-0-0-0-0-0-0-0-0-0-0-0-0-0-0-0-0	2323333247444445334 02193642936777186705987904	3871771389755385999138 025 65874172110155210162578 00120212334555556788897654100003568901590998990	55093593587 4153178833595354627762000000000000000000000000000000000	100 100 100 100 100 100 100 100 100 100

LANDSAT DIGITAL MUSAIC TIEPUIN" DATA SET PENNSYLVANIA MESAIC UTM ZUNG 10 ENITIAL MESAIL GATA BASE

F	MAME	Ile Sea	4121	CEESET	LINE	TO SAMP	FROM	tase Frich Samp	Ĭ.c	FROM	INTERFRA	ME ERH SAMP	DELTA	Z CONFIDENCE TO FROM
	222222222222222222222222222222222222222	320 321 321 322 323 324 23 32 32 32 32 32 32 32 32 32 32 32 32	A SA	3100 9600 3100 9600 3100 9600 3100 9600 3100 9600 3100 9600 3100 9600 3100 9600 3100 9600	5642910 b0 b20542231112 b84156041985966325635231112 b861777-112222223333333445797788655555555555555555555555555555555	\$6689123	00000000000000000000000000000000000000		000000004302195425147713341000351032204998767551	0000000000781675867547587899851069071173651176 00000000000000000000000000000000000	501144987W31405788540W3834W543344W343555380100343	G72835152917670576269848107411377905572477765055	000000006576073161617945448915855266913886993625 0000000003313235420000000000000000000000000000000000	100 100 100 100 100 100 100 100 100 100

PENNSYLVANIA MUSAIC UTM ZUME 16 INITIAL MOSAIC DATA BASE

FRAME	Tiepuini Sea Tre	CFFSCT	LINE	TO SAMP	FREM	LASE FRUM SAMP	70	FROM	INTERFRA LINE	ME ERR	DELTA Z		FRCM
	######################################	3700 9500	4524 4536	2214575933-8745964-415964-225644 2214575933-8748694-445964-225644 221476933-874869-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1	193600 193		154564000493641.206044444444444444444444444444444444444	2445435-83632649108************************************		011-6894-604-273871-0-691117-2333321-00-871-0-644-644-644-644-644-644-644-644-644-6		100 100 100 100 100 100 100 100 100 100	

MOS34 Output Listing UTM Zone 17, Second Date 1981

LANDSAT DIGITAL MUSARL TREPCINT DATA SET

PAGE 1-001

CASE RGM9UU.PAT STEP 4

FRANE SEU TYPE	. CFFSET	LINE	TC SAMP	FROM	FRUM SAMP	TO FROM	INTERFRA LINE	MF ERR SAMP	DELTA-		ENCE FROM
11 11 559 FIX 11 11 11 509 FIX 11 11 11 609 FIX	900 1100 900 1100	00000000000000000000000000000000000000	00000000000000000000000000000000000000	\$54246936385679965426999635117215152595603313255956033132559560331325595603313255956033132559560331325595603313255956033132559560331325595603313255956033132559560331325595603525556033132559560352555560331325595603525555603313255956035255556033132559560352555560352555556035255555560352555555603525555555555		du - 4 = = = = = = = 1	30000000000000000000000000000000000000	0		100 100 100 100 100 100 100 100 100 100	
11 11 080 F1X 11 11 081 F1X 11 11 683 F1X 11 11 085 F1X	900 1100 900 1100 900 1100	2325.50 2325.50 2325.50 2325.50	2112.50 2325.50 2750.50 3175.50	1981.71 1939.44 1853.57 1768.40	244.15 244.15 244.15	11<"14****** 11<"14****** 110°94*****	0.0 0.0 0.0	0.0**	****** ****** ******	100 100 100 100	100 100 100 100

This tiepoint file is used as input to geometrically correct each Landsat scene used in the UTM Zone 17 second date 1981 mosaic.

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FRAME SED TYPE	CFFSET	LINE	SAMP	FROM	PRUM SAMP	TO-	FROM	INTERFR LINE	AME ERR SAMP	DELTA	2 CONFIDENCE TO FROM
11 11 699 FIXX 11 11 700 FIXX 11 11 71 72 FIXX 11 11 11 11 72 FIXX 11 11 11 11 12 FIXX 11 11 11 11 11 11 11 11 11 11 11 11 11	900 1100 900 1100	00000000000000000000000000000000000000	\$5555555555555555555555555555555555555	541183104412062862626262626262626262626262626262626		*************************************	**************************************	00000000000000000000000000000000000000	0.000000000000000000000000000000000000		100 100 100 100 100 100 100 100 100 100

LANDSAT DIGITAL MUSAIC TIEPDINT DATA SET

CASE REMYUU.PAT STEP 4

FRAME SEO TYPE	OFFSET	LINE	SAMP	FROM LINE	FROM SAMP	70 F	ROM Z	INTERFRA LINE	ME ERR	DELTA	Z CONFII	DENCE FRCM
11 11492 FIX 11 111493 FIX 11 111503 FIX 11 111503 FIX 11 111603 FIX 11 11 111603 FIX	1100 1100	1824-50 1914-50 2025-50 21919-50 21919-50 1154-50 15417-50 1417-50 1417-50 1417-50 1417-50 1417-50 1417-50 1417-50 1417-50 1117-50	14458.55000000000000000000000000000000000	8424-835-9-10-0-0-0-0-0-0-0-0-0-0-0-0-0-0-0-0-0-	1453-344 1453-344 1453-344 1453-344 1453-34-20 14		· · · · · · · · · · · · · · · · · · ·	00000000000000000000000000000000000000			100 100 100 100 100 100 100 100 100 100	ORIGINAL PAGE 18 OF POOR QUALITY 9909999999999999999999999999999999999

LANDSAT DIGITAL MUSAIC TIEPGINT DATA SET

CASE REMYDUAPAT STEP 4

FRAME SEY TYPE	OFFSET	LINE	TO SAMP	FROM	FRUM	- <u></u> -	FRCM Z	INTERFRA LINE	ME ERR SAMP	DELTA	DENCE FROM
11 111039 FIX 11 111049 FIX 11 111059 FIX 11 111059 FIX 11 111059 FIX 11 111059 FIX 11 111059 FIX 11 111069 FIX 11 11 11069 FIX 11 111069 FIX 11 1	900 1100 900 1100	20946-000 23137-000 23137-000 1847-000	3286000 3286000 3286000 3286000 3286000 32876000 32876000 32999000 21999000 21999000 21999000 21999000 21999000 229999000 229999000 229999000 229999000 229999.	000 000 000 000 000 000 000 000	143.000000000000000000000000000000000000	0.000000000000000000000000000000000000		00000000000000000000000000000000000000			ORIGINAL PAGE IS OF POOR QUALITY

LANDSAT DIGITAL MUSAIC TIEFDINT DATA SET

CASE RUMYUU.PAT STEP 4

FRAME	TIEPOINT SEU TYPE	OFFSET	TO	TO SAMP	FFOM LINE	FRUM SAMP	<u> </u>	FROM	INTERFE LINE	AME ERR	DELTA	Z CONFIDENCE TO FROM
11 12 11 12 11 12 11 12	マツマシンシンシンシンシンシンシンシンシンシンシンシンシンシンシンシンシンシンシ	1100 1100 1100 1100 1100 1100 1100 110	3175.94 3156.52 3137.14 3118.06 3098.75	2249.12 22153.79 2059.34 1869.10 1773.65 1584.29 1489.03 1298.92 1499.72 1109.43 1209.43 1209.92 1109.93 1209.93	2900.50 2900.50 2900.50 2900.50 2900.50 2900.50 2900.50	\$\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	163421475966208360828142524091978857101676603593080808080808082814252409197885710167660359308055783544334334343434343434344447132503788571016035085788571016766035	5752712549782773525380441150201078570362665245 930858878323421323152024472564474603250273 56666555666666666656666556665666566666156	4689151342618391522561921480883733749378325306	1258120404536761538910535420963145321011033511 0000111000000011000011111111100000000	4011502211210321023201024110312314110763101910 	100 100 100 100 100 100 100 100 100 100

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CASE	KUMYUU	PAI	STEP	4
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FRAME SEU TYPE	OFFSET	FINE	TO SAMP	FROM LINE	FRUM SAMP	<u> </u>	FROM Z	INTERFR LINE	AME ERR SAMP	OFLTA Z	Z CONFIDENCE TO FROM
######################################	100	4429069080808080808080808080808080808080808	69677655 77977655 	00000000000000000000000000000000000000		#2184145011543241876576040499274792986417110348 #5	7209483435396169170853155387793540992859300878 75679551548865219238531679175379404693843024444	1558810136680521807046212114999011556645567808 1	2494537578132575170526767635503U1Q226146132360	0011049934253118607627195111580152014448230633 	100 100 100 100 100 100 100 100 100 100

LANCSAT DIGITAL MUSALL TIEPDINT DATA SET

PAGE 1.007

CASE KOMYUU.PAT STEP 4

FRAME SEU TYPE	OFFSET	LINE	TO SAMP	FROM LINE	FRUM SAMP		FROM Z	INTERFRA LINE	ME ERR SAMP	DELTA	Z CONFIDENCE TO FROM	
11 13 10 10 10 10 10 10 10 10 10 10 10 10 10	900 11000 900 11000	2517944205497417052999974319230579993254484548550117305898748559997431212334521067792311111111111111111111111111111111111	5606439352540337023202139576131839776205 	6.3.3.2.9.7.6.8.8.2.8.3.2.3.2.3.2.3.2.3.2.3.2.3.2.3.2	4.64.600	7936737952068337421818354832906613098678392070860643246800373739700413842642592828745762667	4422239233607435012489543574581036192743804411 442223923360743501248954357252859253606612115520	0677636636152316733366956431221500506012422032 	29354776984U3445U12U8742Z123526037679599679520	7514518321649207699579278772384423m3041715518650	100 10	

LANDSAT DEGITAL MESAIC TEPPERAT DATA SET

CASE RUNSUU-PAT STEP 4

FRAME SEN TYPE	OFFSET	LINE	SAMP	ER OM LINE	FRUM SAMP	7 G	FROM Z	INTERFR	AME ERP SAMP	DELTA	Z CONFIDENCE TO FROM
11 14 07 MJV E 11 14 07 MJV E 11 14 16 MJV E 11 14 17 MJV E 11 14 11 MJV E 11 11 MJV E 11 12 11	3700 400 3700 400 3700 400 3700 400 3700 400 3700 400 3700 400 3700 400 3700 400 3700 400	791.53588111.9695977339485889717.7273488989599999999999999999999999999999999	2584698975886460117516976326011826496698554601182649669855465469175166586959667652601144466985654691111111111111111111111111111111111	29900-50 9000-50 9000-50 9000-50 9000-50 9000-50 9000-50 1000-	242-50 2425-50 2425-50 2425-50 24215-54 24215-50 2	29326967777259220391857527125497827735253804411 0443715008491856000000000000000000000000000000000000	5020596256241301716342147596620836082814252 	2559183321246811814846891513426183915225619214 	1260951129692565804312581204045367615389105354 0001300502129692565804312581204045367615389105354	3198900511012011011	100 100

LANDSAT DIGITAL MOSAIC TIEPOINT DATA SET

CASE NUMBUU PAT STEP 4

	TIEFOIN			SAMP	FRÓM LINE	SAMP	Ţ0 	FROM Z	INTERFR LINE	AME ERR SAMP	DELTA Z	Z CONFI	DENCE
12222222222222222222222222222222222222	00000000000000000000000000000000000000	### ##################################	1672688424853374574334444290000000000000000000000000000000	2853.79 2759.69 2664.34 2569.10	20714352174113627662100343955050528747840501925 567345621741136276621003439550150501925 5550660667774778888889999999518898349484955884494 4444444444444444444444444	1.2009 00155 00 1244 00 1244 00 125 0	50201078570362626257209 4744444444444444444444444444444444444		8088373374937830615588000000000000000000000000000000000	2096314532101103351124945 ***********************************		1000 1000 1000 1000 1000 1000 1000 100	ORIGINAL PAGE IS OF POOR QUALITY 1210200000000000000000000000000000000

LANDISAT DIGITAL MUSALL TREPOINT DATA SET

CASE RUMYUU. PAT STEP 4

FRAME		POINT		FSET	LINE	TO SAMP	FROM LINE	FRUM Samp	70	FROM	INTERFRAI LINE	ME ERR SAMP	OELTA Z	FROM
AND NATURAL PROPERTY OF THE PR	618 622 623 624	PFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFFF	00000000000000000000000000000000000000	00000000000000000000000000000000000000	\$\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	00000000000000000000000000000000000000	733228b002157-405551629437411111111111111111111111111111111111	111777101004010000000000000000000000000	100 - 100 -	**************************************	390099090090090090000000000000000000000			

LANESAT DIGITAL MUSARC TREPDINT DATA SET

PAGE 1-011

CASE NUMBER STEP 4

FRAME SEG TYPE	OFFSET	LINE	SAMP	FROM	FREM SAMP	70	FREM	INTERFRAN LINE	SAMP	DE LTA		PROM
	\$700 400 \$700 400 \$70	00000000000000000000000000000000000000	00000000000000000000000000000000000000	8221129686800221118725545816668526118725545867753966852273-96		11009961-23845495357006271677268454444141414141414141414141414141414141		00000000000000000000000000000000000000			1000 1000 1000 1000 1000 1000 1000 100	

LANDSAT DIGITAL NUSARE TREPOINT DATA SET

CASE RUMSUULPAT STEP 4

FRAME SEG TYPE	CFFSET	LINE	TC SAMP	FROM LINE	FRUM SAMP	TØ FRQ 2 2	LINE	AME ERR SAMP	DÉ LTA Z	ENCE FROM
12 12 12 12 12 12 12 12 12 12 12 12 12 1	3700 4000 3700 4000 3700 4000 37100 4000	00000000000000000000000000000000000000	00000000000000000000000000000000000000	244229854198517604602244481499997614000000000000000000000000000000000000	7108084304014030403070000000000000000000000000	124 - 30 - 30 - 30 - 30 - 30 - 30 - 30 - 3				ORIGINAL FAGE 18 OF POOR QUALITY SSSSSSSSSSSSSSSSSSSSSSSSSSSSSSSSSSS

LANDSAT DIGITAL MUSAIC TIEPDINT DATA SET

PAGE 1.013

CASE KOMBUUSPAT STEP 4

FRAME SES TYPE	OFFSET	LINE	TC SAMP	FROM	FROM SAMP	†0 2	FRCM	INTERFRA L INE	ME EPP SAMP	DELTA	Z CONFI	DENCE FROM
FILLY X X X X E RECUES ESTABLISHED STATES AND	3700 400 3700 400	774-00000000000000000000000000000000000	2488.79	222222 2000000000000000000000000000000		U.U**	**************************************	00000000031638199434225677321211101622480402 000000000777771210101622480402	0.0** 0.0** 0.0** 0.0** 0.0**	**************************************	1000 1000 1000 1000 1000 1000 1000 100	

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LANDSAT DIGITAL MESALE TIEPOINT DATA SET

CASE REMYDUL PAT STEP 4

FRAME SEU TYPE	OFFSET	LINE	TO SAMP	FROM LINE	FROM SAMP	TO 2	FROM Z	INTERFR.	AME ERR SAMP	DELTA Z	Z CONFIDENCE TO FROM
14 99 MUNUME 14 14 14 14 14 14 14 14 14 14 14 14 14	37000 4000 37000 37000 37000 3	47790241 •17902	6936224474934037046189101077736568347474937068370411624747150685734441891101077736660756834747124713333444445145144457777109926878434754437247147111144457777109926878434372471451444577711019268784343724714514445714514443724714514443724714514443724714514345144437247145144437437451444374437443744374437443744374437443744	9317918415324663105686256284693758655-449887-446636-5-44698170-5-6-5-5-5-5-5-6-5-5-5-5-5-5-5-5-5-5-5-	\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	4000715673563784724153547658683435396169174853 327857657126834354354763571534765521548850 66656666666666666666666666666666666	2477986048502370586929409012414501543241876576 9493042416649814659291385702664903844915436163 9493042416649814659291385702664903844915436163	3223138257254708682253111412110136680521807046 0000000000000000000000000000000000	3166649661245409860910897492637578132575170526	85778839475040796852786062464849934253118607627 522582343547146065675462222232300151042416520216 1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1	100 100

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CASE KUMYUU PAT STEP 4

FRAME SEG TYPE	OFFSET	LINE	SAME	FROM	frûm Samp	70	FROM Z	INTERFR.	AME ERR Samp	DE LTA	Z CONFIG	DENCE FROM
11 445 MMDD 20 VVVVVVVVVVVVVVVVVVVVVVVVVVVVVVVVVV	31000 31000	77283304-4420415-19133-1	3349394928618889522714956064393376232722171420756415326948267788899152272252469159494949494949494949494949494949494949	3443782766650000000000000000000000000000000000	3199442333333333333333333333333333333333	1553877935489928593038784422239233687435012489 6771753774946928433244449327561264928718142	0404992747929864171103487936737952068337421818 346545185455454947555378606435468303737179996	2121149990115566455678080677636636152316733366	7676355030102261461323602935477698403445012087 00000000000000000000000000000000000	195±115801520144482006307514518321649207699579 3864907040444024503310171389003063250216530152	1000 1000 1000 1000 1000 1000 1000 100	

CASE KUMSUUSPAT STEP 4

FRAME SEE TYPE	PEFSET	IO LINE	SAMP	FHCM LINE	FRUM 54 mP	16 <u>7</u>	FRIDM Z	INTEPFRA LINE	ME EHR SAMP	DELTA		PROM	
13 13 524 FILA A	900 3100 900 3100	90000000000000000000000000000000000000	10000000000000000000000000000000000000	93352657446320080724435035357083840070599884044435 61.2.7908787878787878787878787878787878787878	120 - 20 - 20 - 20 - 20 - 20 - 20 - 20 -	24.00***********************************		90000000000000000000000000000000000000	0.0** 0.0**		100 100 100 100 100 100 100 100 100 100		ORIGINAL PAGE IS

LANDSAT DIGITAL MUSARC TREPCINT DATA SET

PAGE 1.017

CASE RUMBUU-PAT STEP 4

13 13 610 FIX 900 3100 1275-50 1487-50 1129-8½ 1217-33 d7-3******* 0.0 0.0******** 13 13 610 FIX 900 3100 1275-50 1487-50 1129-8½ 1217-33 d7-3****** 0.0 0.0******** 14 13 613 FIX 900 3100 1275-50 1912-50 1090-84 14su-72 91-9******* 0.0 0.0********* 14 13 613 FIX 900 3100 1275-50 1912-50 1051-35 kosz-57 yi-8****** 0.0 0.0********* 14 13 613 FIX 900 3100 1275-50 2125-50 1051-35 kosz-57 yi-8****** 0.0 0.0********** 14 13 613 FIX 900 3100 1275-50 2125-50 1051-35 kosz-57 yi-8******* 0.0 0.0************************	00 100 00 100 00 100 00 100 00 100 00 100
13 13 615 F1K 900 3100 1275.50 2762.50 895.40 423.21 494.40 42.71 40.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.0 0.	00 100 00 100 00 100 00 100

LANDSAT DIGITAL MUSAIC TIEFOINT DATA SET

CASE RUMBOULPAT STEP 4

FRAME SEA TYP	t OFFSET	TO	TO SAMP	FROM LINE	FRUM	70	FROM Z	INTERFR LINE	AME ERR SAMP	DELTA		DENCE FROM
13 13 674 FIXA 000924 FIXA 000924 FIXA 13 0077 FIXA 13 13 0077 FIXA 13 13 0077 FIXA 13 13 13 13 0077 FIXA 13 13 13 13 13 13 13 13 13 13 13 13 13 1	9000 311000 9000 311000	00000000000000000000000000000000000000	00000000000000000000000000000000000000	908884481894423652946818701002221788734080573138819788021	1412974743103 +014330077111700774400710771077077107774007710777107770777			\$\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	G. G		1000 1000 1000 1000 1000 1000 1000 100	ORIGINAL PAGE IS OF POOR QUALITY 11111111111111111111111111111111111

LANDSAT DIGITAL MUSAIC TEPPEINT DATA SET

CASE KUNYUU.PAT STEP 4

FRAME SEJ TYPE	OFFSET	LINE	SAMP	FROM LINE	FRUM SAMP	Ţ0 2	FROM Z	INTEKER!	AME ERR SAMP	DE LTA		FROM
TEXAXX	1000 1100	00000000000000000000000000000000000000	00000000000000000000000000000000000000	377887554760774157858721430580692398348381064250 90.96875574760741578858721430580692398348381064250 90.968755777664068877575575555555555556666665555777768406887797579799999999999999999999999999999	1440 1440	09444444444444444444444444444444444444		00000000000000000000000000000000000000	0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0** 0.0**	**************************************	1000 1000 1000 1000 1000 1000 1000 100	11000000000000000000000000000000000000

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LANDSAT DIGITAL MUSARE TREPORNT GATA SET

CASE RGM900-PAE STEP 4

FRAME SEU	LANE FOINT	CFFSET	LINE	SAMP	FROM	FRUM SAMF	70	FROM	INTERFRA L INE	ME ERR SAMP	DELTA	Z CONFIDENCE TO FROM
13 14 91 13 15 22 13 15 22 13 15 22 13 15 20 13 15 20 13 15 20	A A C C + C A A A A A A A A A A A A A A	31000 31000	180648130771111577399357033703441770442203574681992464584776801937708645847770442203574683344175311024642175317086491367913515797531877531877531333333333333333333333333	81042356666774411193186016301638640016386401638640163864016386401638640163864016386401638640163864001638640016386400163864001638640016386400163864001638640016386400000000000000000000000000000000000	811900 66.621900 66.621900 66.621900 66.621900 66.621900 66.621900 66.621900 67.62100 6		4143679380095104051599683664282082563312034E15	3232679479974214051510773864171103488678753718 41310572790627255442073860954947555572625209443	342244442HI3222LIHHQ2222222224HIQ2201575202H2Q2 000000	1000110014713820987654208557876554464004166738 222222223322211111111100000000000000000		ORIGINAL PAGE (1) OF POOR OUALITY OF POOR OUALITY 1000 1000 1000 1000 1000 1000 1000 10

CASE HUMYUU.PAT STEP 4

LANG 2	LEPGINT EO TYPE	OFFSET	TO.	TO SAMP	FROM LINE	FRUM SAMP	10 2	FROM	INTERFR LINE	AME ERR SAMP	DFLTA Z	Z CONFIDENCE TO FROM
155555588 15555555588 15555555555555555	うらく ちょうしょう かんしょう かんしょう かんしゃく かんしゃく かんしゃく かんしゃく かんしゃく かんしゃく かん かんしゃく かんしゅう かんしゅう かんしゅう かんしゅう しゅうしゅう しゅう	900 3100 900 3100 900 3100 900 3100 900 3100 900 3100 900 3100 900 3100	673284-3326 673281-3326 673281-3326 10177-8281-3326 10177-8281-3281 11209-25-3918 11209-25-3918 11209-25-3918 11209-28	42466.39 2237J.79 2276.03 22297.83 22396.22 23366.39 22389.39 22411.80 22457.39 22480.25	1733-77 1656-74 1561-05 1464-60 1369-23 1271-90 1174-90	3293-500 	3514621092617682332922234147421144361474943455237423867132386713238671325867132586713258671325867185	\$55054183528203429801949968223232324634540290686630430454555554554554555555555555555555	13141213953145450820919296764012X321246324 000000000000000010H1010100000000000000	2384267740124085177629341416885142177569911292 22001222221001111011110000000000	8094180967436667044013845564299827837830593265 557767898982899897879786977764898089899909090909090909090909090909090	100 100 100 100 100 100 100 100 100 100

LANDSAT DIGITAL MUSALL TEPPINT BATA SET

CASE KGMYUU-PAT STEP 4

FRAME SEU T	NT WE OFFSET	LINE	TO SAMP	FROM	FRUM SAMP		FROM Z	INTERFR LINE	AME ERR	DELTA	Z CONFI	DENCE FROM
######################################	No. No.	13240-426 8-9447 8-9447-426 8-447-426 8-447-426 8-447-426 8-548-439 8-548-439 8-548-439 8-548-439 8-548-439 8-548-439 8-548-439 8-548-439 8-548-439 8-648-339 8-648-339 8-648-339 8-648-339 8-648-339 8-648-339 8-648-339 8-648-339 8-648-339 8-648-339 8-648-339 8-648-339 8-648-339 8-648-339 8-648-339 8-648-339 8-749-339 8-	1996582 2496582 199658	988-435-84-63-63-63-63-63-63-63-63-63-63-63-63-63-	4450114720000000000000000000000000000000000	31095497024349360224631012288400966009141170935 731284	753854750560724914U91893860679479974142615654862655555555555555555555555555555555	3661286343524453175727227218663111053033525564 0000000000012344444444311100000000000000	10000000000000000000000000000000000000	6682012296827797882545273622716278268735024787 00942012296827797882545273622716278268735024787 11 21 1 45975887577565868576676887087579419302	100 100 100 100 100 100 100 100 100 100	ORIGINAL PRESENTA

EANDSAT DIGITAL MUSAIL TREPORNT DATA SET

CASE KUMYUU.PAT STEP 4

FRAME SEU TYPE OFF		TO FROM	FRUM SAMP	76 2 	FROM	INTERFRAME ER	PZ	2 CONFIDENCE TO FROM
5 MJVE 37000 2225 14 11	100 151-08 112 100 169-44 123 100 169-64 14 100 1205-64 15 100 224-79 17 100 224-79 16 100 224-79 16 100 224-79 16 100 321-93 15 100 321-93 15 100 439-72 16 100 533-72 11 100 567-79 11 100 567-79 11 100 567-79 11 100 567-79 11 100 567-79 11 100 567-79 11 100 567-79 11 100 567-79 11 100 567-79 11 100 567-79 11 100 567-79 11 100 567-79 11 100 567-79 11 100 567-79 11 100 567-79 11 100 567-89 15 100 459-88 13 100 672-69 14	27.87 100.50	00000000000000000000000000000000000000	7458103619274380441150205962966083608508997205 00000000000000000000000000000000000	3290661309867839207029326967555554555455555555555555555555555555	00000000000000000000000000000000000000	3844231041755186503148900536842693451281944 442333041715540033492229217878787885674673482	ORIGINAL PAGE & OF POOR QUALITY 1000 1000 1000 1000 1000 1000 1000 10

EANDSAT DIGITAL MUSAIC TIEPDINT DATA SET

CASE RUMSUU.PAT STEP 4

FRAME SEA	OINT TYPE OFFSET	FINE	TO SAMP	FROM	FRÚM Samp	76	FROM Z	INTERFRA LINE	ME EPP SAMP	DELTA Z	Z CONFIDENCE TO FROM
144444 112222223455558888888999999999999999999999999999	37000 225000 00 00 00 00 00 00 00 00 00 00 00 00	4485981294424643380322441179011351372454595757812222222222222222222222222222222222	681444705563288807119869362244749340891251105077 9860395583528761883818429380118912511000577 308438528687658838184257865838888959948868675251888889599488675251888888959948867724724791595555555555555555555555555555555555	033044911094608887000000000000000000000000000000000	111437-7-14	3336628945UU5154U12477986U485U23705869294U9U12 9878278U3460U394943U444166498446572913857U2	9671718044860600794000715673563784724153547658 •••••••••••••• •••••••••••• •5555565654555565656655666556	2121110162224804023223138257254738682253111412 000000000000000000000000000000000	5245254266629986633166640661245469860910897492 	68659112112455554828577839475040796852786062464	100 100 100 100 100 100 100 100 100 100

LANDSAT DIGITAL MUSALL TIEPOINT DATA SET

PAGE 1.025

CASE KOMMUU.PAT STEP 4

FRAME	TIEPUINT SEU TYPE	OFFSET	TO Line	SAMP	FROM LINE	FREM SAMP	10 2	FROM Z	INTERFR LINE	AME_EKR _SAMP	DFLTA Z	Z CONFIDENCE TO FROM
14 13 14 13 14 13 14 13 14 13 14 13 14 13	アドントのものものものものできないといいといった。 まんとうしゅう ちゅうかん アドントのもの でんじついん 大き ア・ア・ア・ア・ア・ア・ア・ア・ア・ア・ア・ア・ア・ア・ア・ア・ア・ア・ア・	3700 25000 3700 25000	91198603677034987.70349077418307711111111222222233333444444455555566655555444437588	3059425 b9 34 6 141 47 87 86 94 22 90 1 8 8 1 6 6 7 7 4 1 1 2 2 2 3 3 1 1 1 1 1 1 1 1 1 1 1 1 1	44.54 44.59 44.64 45.09 45.37 45.39 45.49	20000000000000000000000000000000000000	445741U57774403088875254347283232679474974214U5 55655552425742572568875283232679474974214U5 556555524356887525434151U572747405455555	6548329066133008957425402628414367938009510405 31081264259286881439158893134135727016272554 55655554554555555555555555555555555	10#220#1222333#11111110334311342244442113222111 400000000000000000000000000000000	4534567886369258902349135163100011001471382098	8112021410313200130110022110010011111000 -0000000000000000	100 100 100 100 100 100 100 100 100 100

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CASE RUNYUU-PAT STEP 4

FRAME SED TYPE	OFFSET	LINE	TO SAMP	FR OM LINE	FRUM SAMP	Ţ0 	FROM	INTERFRA	AME ERR SAMP	DELTA Z	Z CONFI	DENCE FROM
91 MIXX A X A X A X A X A X A X A X A X A X	37000 25000 37000 25000 37000 25000 37000 25000 37000 25000 37000 25000 37000 25000 37000 25000 37000 255000 37000 255000	9935511 155811 1.	836016304240557231344055572313440555723134405555555555555555555555555555555555	43284395743594361886928562123344553858456212334445538584562123344553858456215888562123344553455365842011111111223341627735912114451111111111111111111111111111111	1907-0-10-10-10-10-10-10-10-10-10-10-10-10-1	1510773864171103481283454545454545500255025025025025025025025025025025025		192222222222222222222222222222222222222	1		1000 1000 1000 1000 1000 1000 1000 100	1000 1000 1000 1000 1000 1000 1000 100

LANDSAT DIGITAL MUSAIC TIEPDINT DATA SET

CASE RUMYUU-PAI STEP 4

FRAME SEU TYPE	OFFSET	LINE	SAMP	FROM	fnim SAMP	Ţ0 2	FROM: Z	INTERFR.	AME ERR SAMP	DELTA	DENCE FROM
######################################	25000 225	00000000000000000000000000000000000000	00000000000000000000000000000000000000	276584047520972038854114060061427755978821489518106201148388888888888888888888888888888888	0412-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-1-	$\begin{array}{c} \bullet \bullet$		030000000000000000000000000000000000000			ORIGINAL PACE IS OF POOR QUALITY 11111111111111111111111111111111111

LANDSAT DIGITAL MESAIC TIEPCINT DATA SET

CASE KUNYUU-PAT STEP 4

	FSET LINE		FROM LINE	FROM SAMP	TO FROM	LINE	SAMP	DELTA Z	DENCE FROM
14 14 613 FIX 37000 14 14 615 FIX 37000 14 14 616 FIX 37000 14 14 617 FIX 37000 15 FIX 37000 16 FIX 37000 16 FIX 37000 17 FIX 37000 17 FIX 37000 18	2500 1275.50 2500 1275.50 2500 1275.50 2500 1275.50 2500 1275.50 2500 1275.50 2500 1275.50 2500 1275.50 2500 1275.50 2500 1487.50 25500 1487.50 25500 1487.50 25500 1487.50 25500 1487.50 25500 1487.50	1627-5-5-5-5-5-5-5-5-5-5-5-5-5-5-5-5-5-5-5	6879066899766879068798788289789898989898989898989898989898	4141048340000000000000000000000000000000	Color Colo				ORIGINAL PAGE 18 OF POOR QUALITY

LANDSAT DIGITAL MUSAIL TIEPDINT DATA SET

PAGE 1.029

CASE RUNGOU-PAT STEP 4

FRAME SEQ TYPE	OFFSET	LINE	TC SAMP	FROM LINE	FRUM- SAMP	ţo.	FROM	INTERFRAME LINE	EPR SAMP	DELTA	Z CONFI	DENCE FROM
14 14 711 FIX 14 14 711 FIX 14 14 711 FIX 14 14 711 FIX 14 14 712 FIX 14 14 723 FIX 14 14 725 FIX 14 14 725 FIX 14 14 720 FIX 14 14 731 FIX 14 14 731 FIX 14 14 748 FIX 14 14 748 FIX 14 14 748 FIX 14 14 749 FIX	25000 25000	2975.50 2975.50 2975.50 2975.50 2975.50 2975.50	2873.50 962.50 1600.50 1812.50 2025.50 2237.50	2339.59 2905.64 2786.49 2746.52 2706.46 2666.58	\$\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\\	7-1-1		30000000000000000000000000000000000000			1000 1000 1000 1000 1000 1000 1000 100	

CASE NGMYUU-PAT STEP 4

FRAME SEJ TYPE	CFFSET	LINE	SAMP	FROM	rkum Samp	Ť0	FROM Z	INTERFRAM LINE	F ERR SAMP	DELTA		ENCE FROM
14 14 14 14 14 14 14 14 14 14 14 14 14 1	25000 25000	00000000000000000000000000000000000000	00000000000000000000000000000000000000	97749977499777788555500 2222222222222222222222222222222	######################################	0.044 0.044 0.044 0.044 0.044 0.044 0.044 0.044 0.044 0.044 0.044 0.044	*****	00000000000000000000000000000000000000	0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0*** 0.0***	**************************************	100 100 100 100 100 100 100 100 100 100	1000 1000 1000 1000 1000 1000 1000 100

LANESAT DIGITAL MUSALC TIEPDINT DATA SET

PAGE 1.031

CASE NUMBUU-PAT STEP 4

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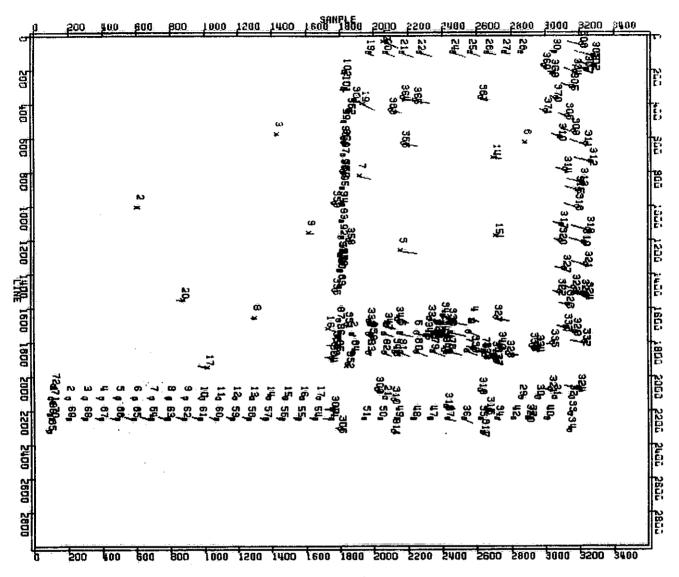
6.3.4 Tiepoint Editing

This phase of the mosaic construction is perhaps the most critical. It is imperative that all 'bad' points be adjusted or discarded, because the accuracy of the mosaic depends on the goodness of the tiepoints.

At this stage a preliminary plot is produced to view the spatial distribution of all points selected. This is necessary to ensure that an even distribution of points is gathered and that no large segments of the imagery are left uncontrolled. If there are large gaps, manually selected tiepoints can be inserted to fill the space the automatic mode was unable to provide for. manual mode refers to the analyst actually identifying common points in two images on a CRT and submitting those points to the standard correlation algorithm for 'locking in'. These can be added to the tiepoint file by repeating steps MOS31 through MOS34. As for the timing of these steps, the 'MOS' procedures typically consume less than 5 minutes CPU total on an IBM 370/158. Another plot can be produced to depict the location of each tiepoint in a cartoon frame. Each tiepoint can possess a tail whose length in pixels is the deviation from a least squares surface for the entire mosaic. This plot aides the analyst in flagging errant points which are not readily identifiable in the tabular listing. If there is such a density of points that only confusion results, the plots can be sectioned to yield better resolution and separation for viewing. Figures 33 through 50 show the distribution of the points used for each frame.

Finally, a plot is produced which looks at the relationship between neighboring points. This plot is called a 'neighbor plot' and is intended to identify juxtaposed tiepoints which disagree on geographic destination. Closely positioned points that are to be moved in different directions can produce 'rips' in the mosaic. This phenonema is seen mainly in the edge matching points and usually only edge matching points are discarded in the editing process. Occasionally a ground control point will be discarded, but only after serious consideration has been given to its validity. A tabular listing of all bad neighbors showing line/sample position is produced to aide in the process.

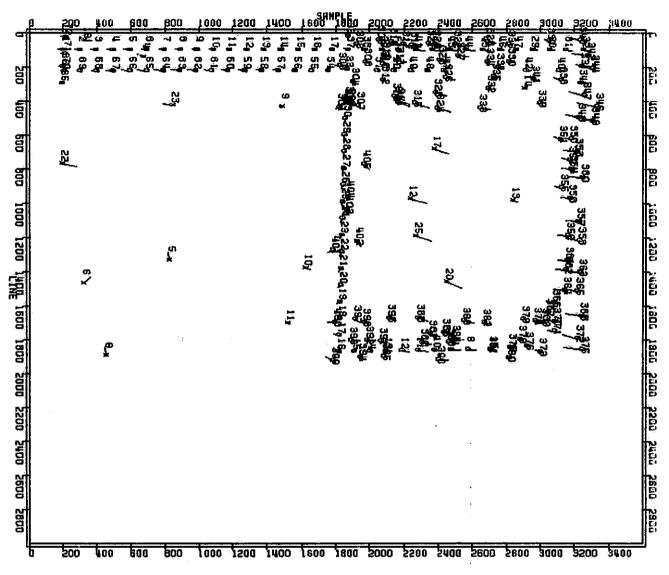
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FRAME 1 SCALE 10.0

Distribution of tiepoints used for Frame 1 Titusville 21267-15031
UTM Zone 17

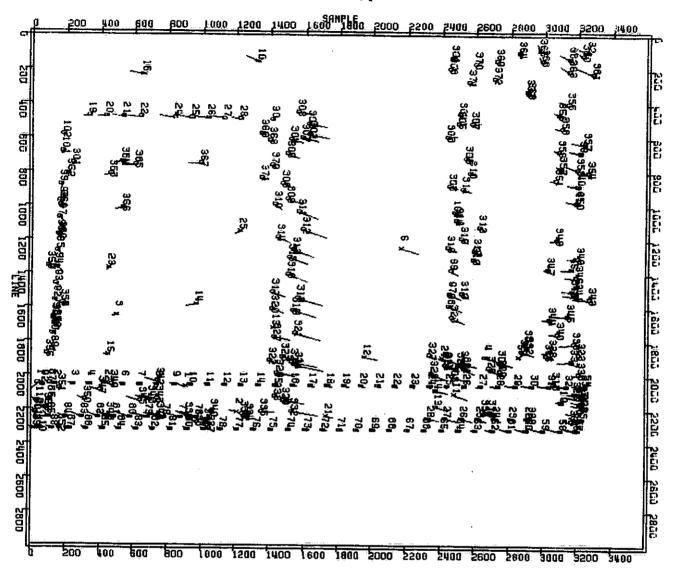
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FRAME 2 SCALE 10.0

Distribution of tiepoints used for Frame 2 Steubenville 21267-15034 UTM Zone 17

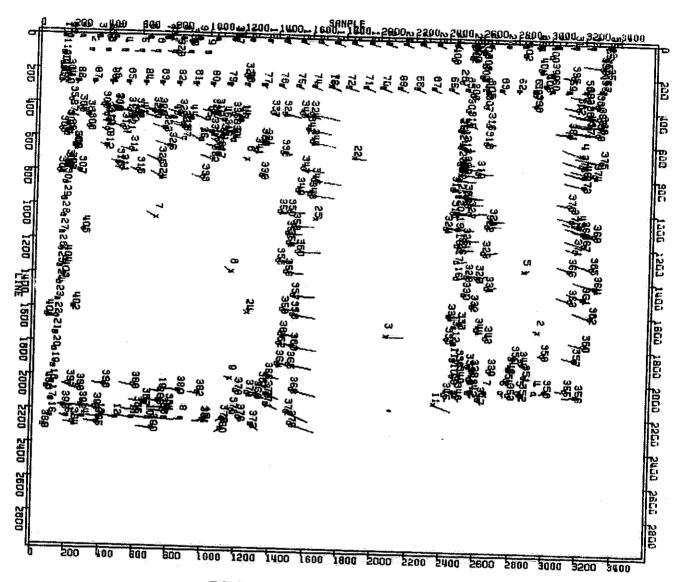
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FRAME 3 SCALE 10.0

Distribution of tiepoints used for Frame 3 Warren 2600-15094 UTM Zone 17

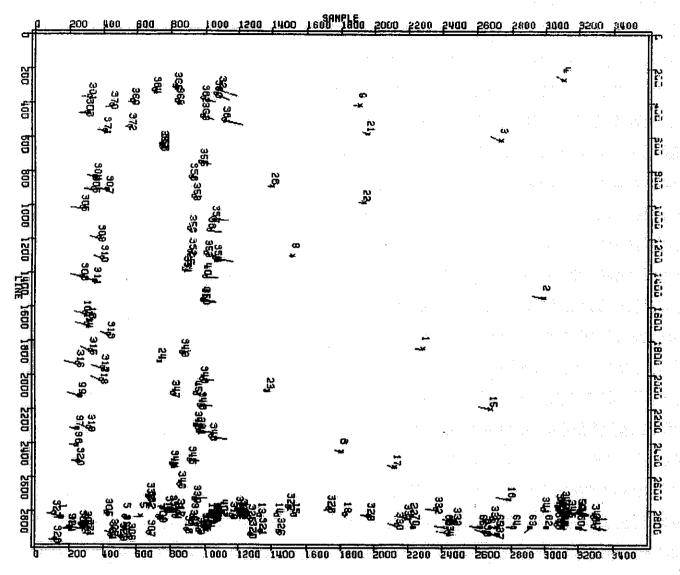
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FRAME 4 SCALE 10.0

Distribution of tiepoints used for Frame 4 Pittsburgh 2600-15100 UTM Zone 17

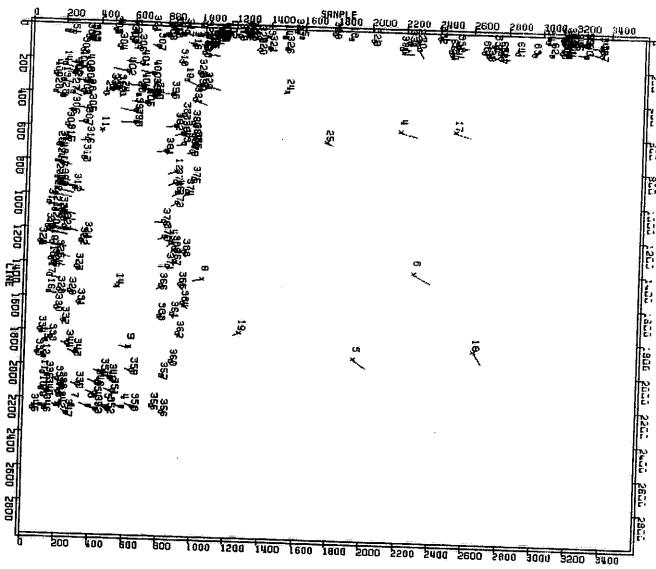
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FRAME 5 SCALE 10.0

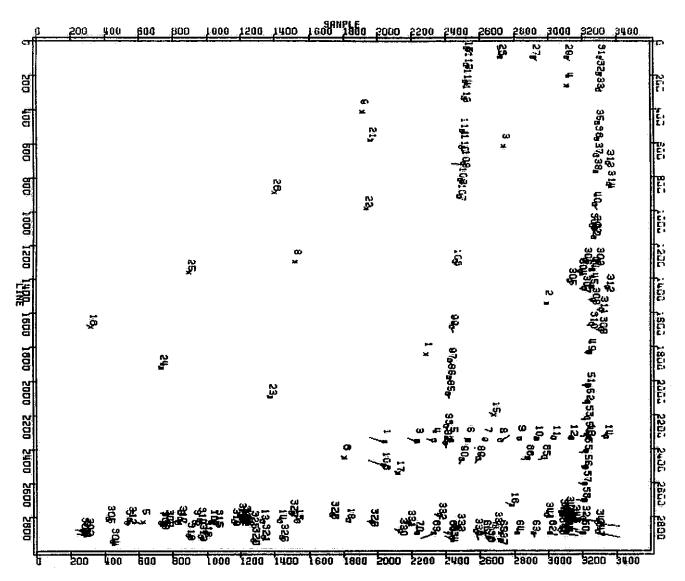
Distribution of tiepoints used for Frame 5 Williamsport 30478-15123 UTM Zone 17

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FRAME 6 SCALE 10.0

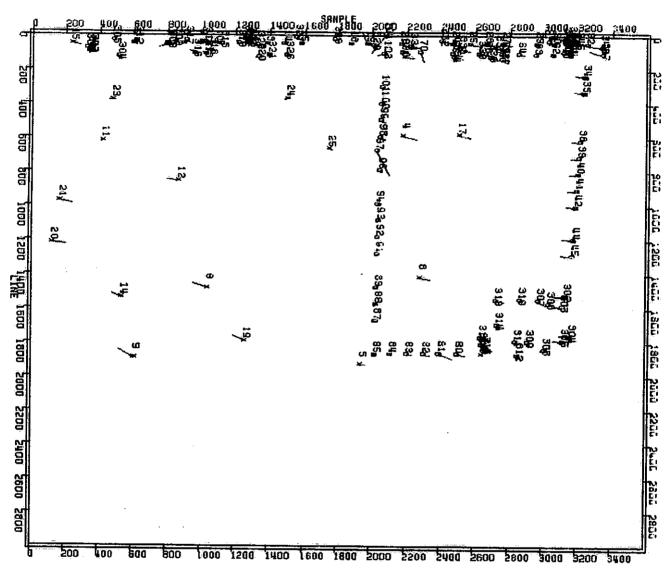
Distribution of tiepoints used for Frame 6 Harrisburg 30208-15141
UTM Zone 17



FRAME 5 SCALE 10.0

Distribution of tiepoints used for Frame 5 Williamsport 30478-15123 UTM Zone 18

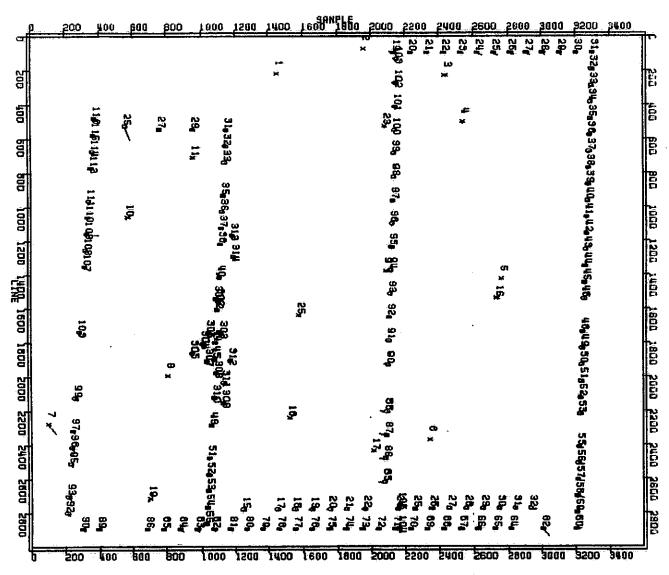
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FRAME 6 SCALE 10.0

Distribution of tiepoints used for Frame 6 Harrisburg 30208-15141

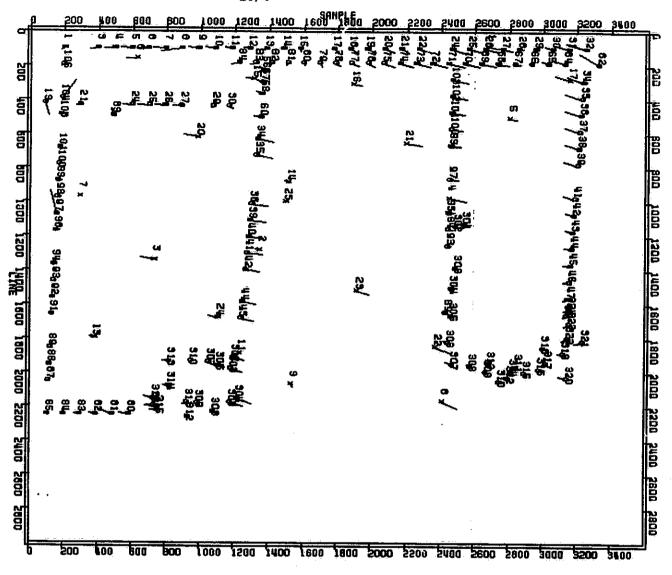
UTM Zone 18



FRAME 7 SCALE 10.0

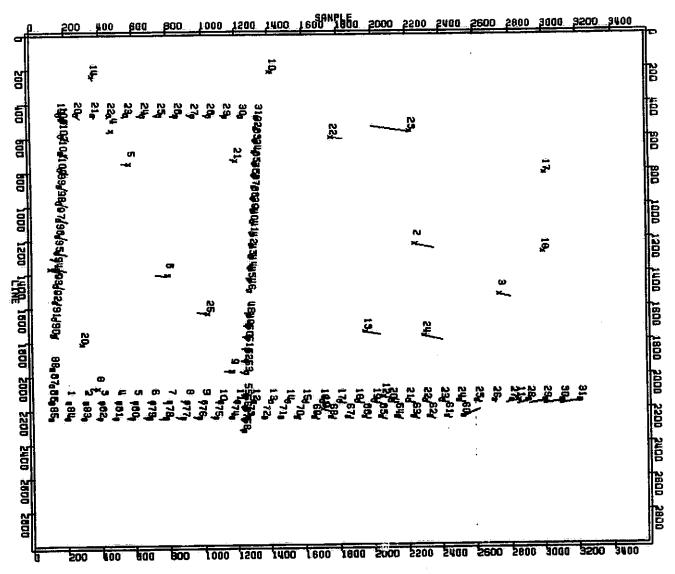
Distribution of tiepoints used for Frame 7 Scranton 21660-15005 UTM Zone 18

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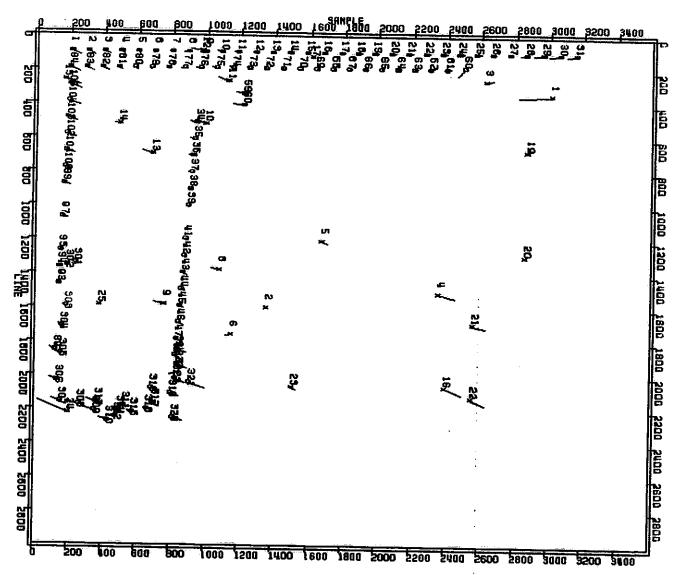
FRAME 8 SCALE 10.0

Distribution of tiepoints used for Frame 8 Lebanon 2544-15001 UTM Zone 18



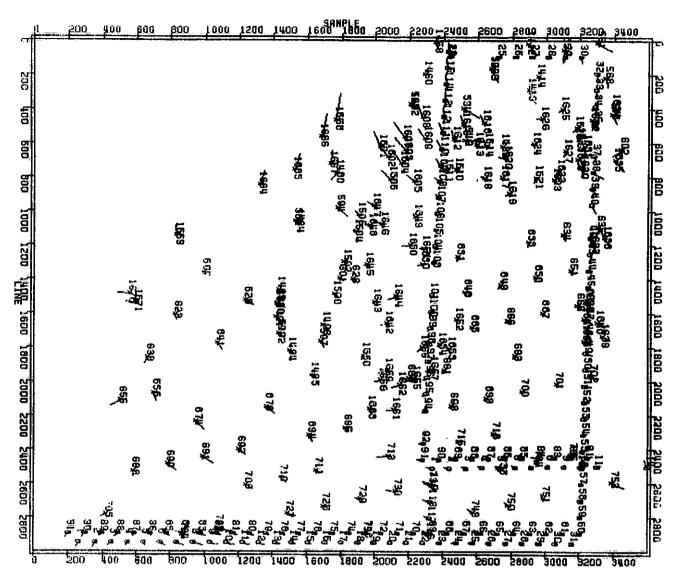
FRAME 9 SCALE 10.0

Distribution of tiepoints used for Frame 9 Poughkeepsie 30170-15020 UTM Zone 18



FRAME 10 SCALE 10.0

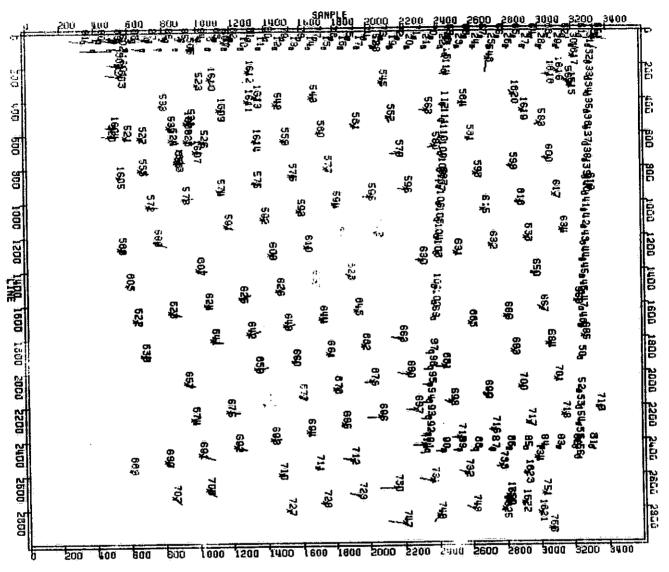
Distribution of tiepoints used for Frame 10 Trenton 30098-15013
UTM Zone 18



FRAME 11 SCALE 10.0

Distribution of tiepoints used for Frame 11 Titusville 22311-15214 UTM Zone 17 Second Date 1981

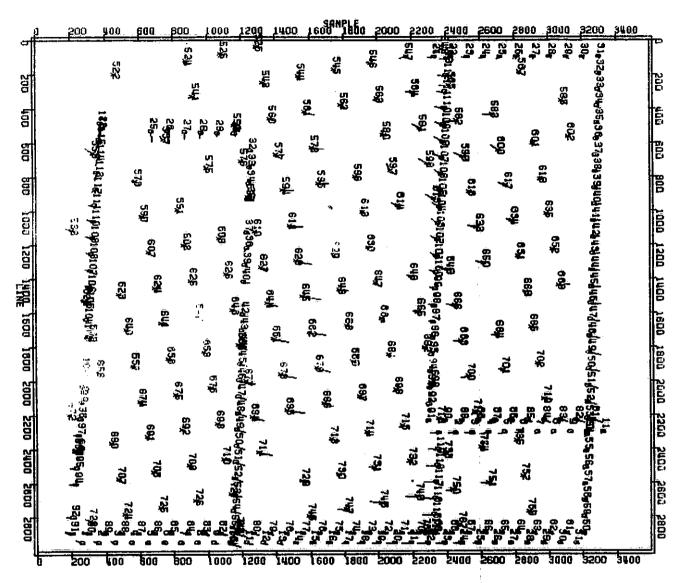
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FRAME 12 SCALE 10.0

Distribution of tiepoints used for Frame 12 Steubenville 22311-15220 UTM Zone 17 Second Date 1981

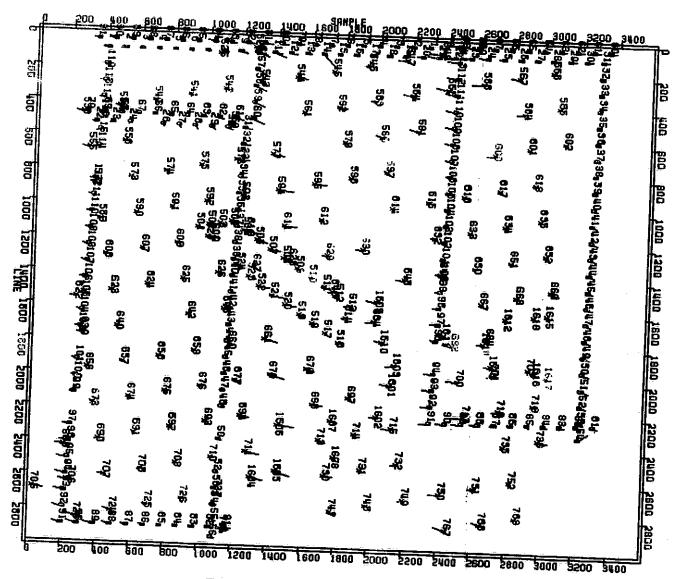
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FRAME 13 SCALE 10.0

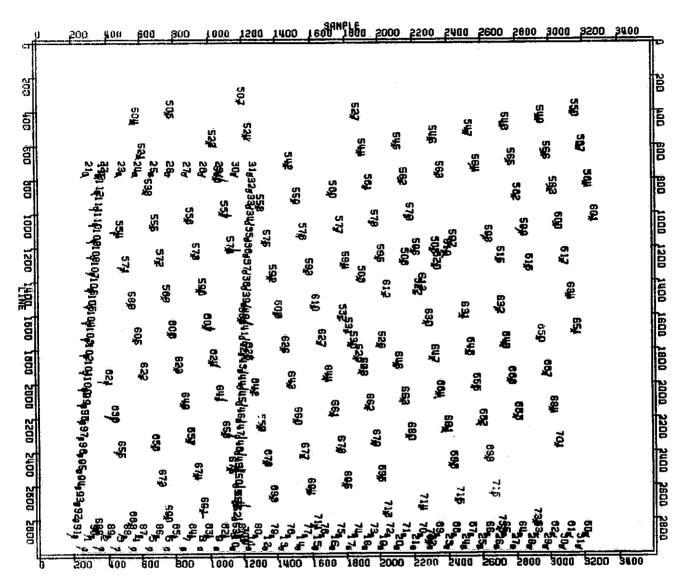
Distribution of tiepoints used for Frame 13 Warren 22400-15142 UTM Zone 17 Second Date 1981

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FRAME 14 SCALL 10.0

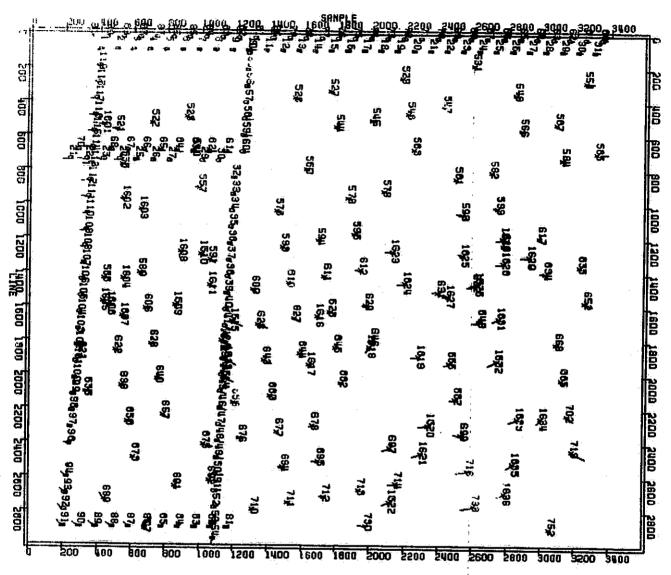
Distribution of tiepoints used for Frame 14 Pittsburgh 22400-15144 UTM Zone 17 Second Date 1981



FRAME 15 SCALE 10.0

Distribution of tiepoints used for Frame 15 Williamsport 22381-15084 UTM Zone 17 Second Date 1981

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FRAME 16 SCALE 10.0

Distribution of tiepoints used for Frame 16 Harrisburg 22381-15090 UTM Zone 17 Second Date 1981

Once the editing has been completed, the entire process is reviewed to insure that nothing has been overlooked. Upon final approval, the next procedure is initiated.

6.3.5 MOS35

The purpose of the MOS35 procedure is to obtain the brightness values for each tiepoint location for all bands of the data sets. This information is necessary in order to smooth brightness differences between scenes.

For each tiepoint which remains after editing, the line/sample position is obtained from the 'From' columns as seen in the MOS34 listing (Tables 6, 7, 8). That point in the raw Landsat image is addressed and a 12 x 12 pixel average brightness is calculated for the point and stored back in the file. Each subsequent point for the scenes is calculated and stored accordingly.

After all points are processed for one band, each successive band is processed until all information is gathered. Once this step is completed, processing can proceed to geometric and radiometric correction.

6.3.6 MOS36

The MOS36 procedure is used to geometrically and radiometrically correct each frame based upon the information in the selected tiepoints. The output is a tape file of the image adjusted to the proper pixel size, rotated north, and trimmed around the perimeter file. These corrected data sets are used as input for mosaicking.

6.3.6.1 Algorithm Theory

The geometric correction consists of two steps. First, a surface fit to the control points is performed and the transformation is evaluated at a uniform grid. Second, the uniform grid is used in an efficient process to transform the image geometrically. For purposes of efficiency, the brightness

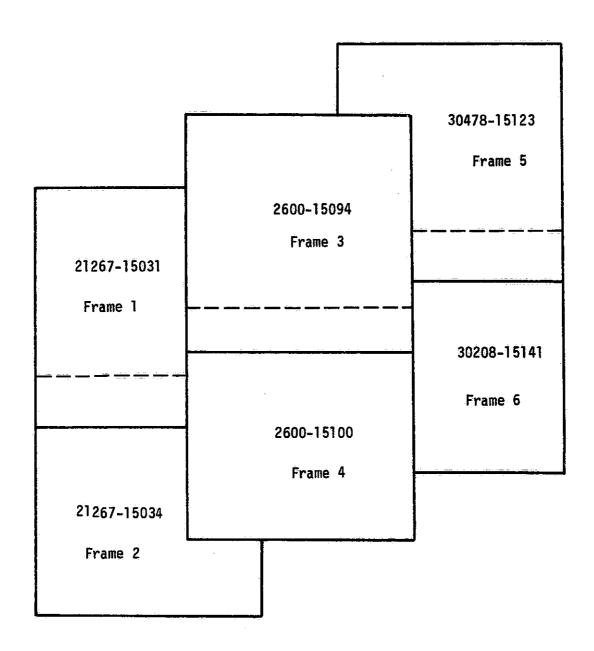
corrections are also calculated to this grid and are applied to the image in the same computation. Within each grid cell, bilinear interpolation is used to determine the amount of geometric shift for a pixel and the amount of brightness correction. The interpolation for a pixel value is also bilinear. The routine, MZGEOM, uses an advanced technique for staging image data from disk storage to memory so that rotation of large data sets can be performed in a rapid manner.

6.4 Mosaicking

Once all frames are corrected for at least one band, a mosaic is constructed. This process is a fairly simple computation but requires large amounts of machine resources to complete. Large mosaic jobs are generally run during off-peak hours. Two tape drives are used at most, so large amounts of disk space have to be reserved. This project required six data sets, 3600 records by 3800 bytes per record, plus an output data set allocated 6500 lines by 8500 samples. The output data set has to be disk since the IPL installation limits the 9-track tape density to 629 bits/cm (1600 bits/in.), and 732 m (2400 ft) of tape at this density are insufficient to store such a large image.

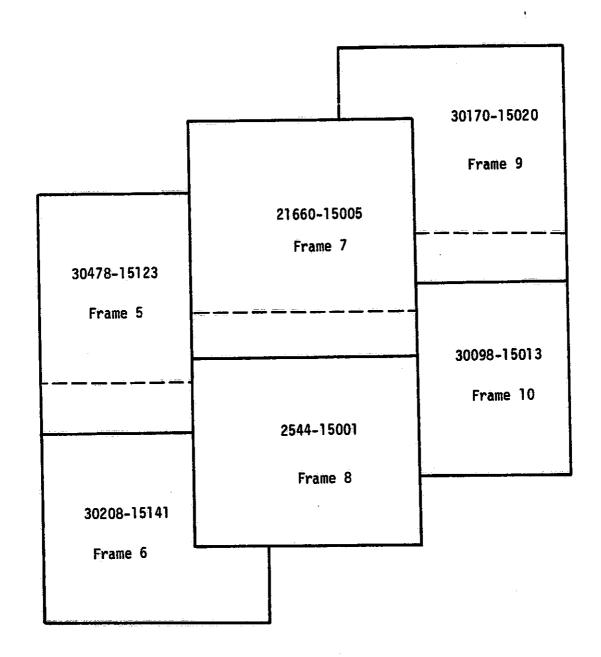
After all data sets are read into a disk file, they are submitted to the mosaicking algorithm that actually does the stitching together. The order of precedence is selectable as is the output frame size. The offsets are specified as parameters to the program and are derived from the MOS34 listing (Tables 6, 7, 8). Since the origin of the output grid is far removed from the actual mosaic, an additional offset, the Master Offset, is subtracted. The order of precedence is determined by the order in which the input data sets are specified. The first data set specified has top priority while the second data set specified has next priority and so on. The mosaicking arrangements used in each mosaic are shown in Figures 51, 52, and 53.

The output data are initially stored on disk and operated on later to extract the individual quadrangles. After the quadrangles are extracted the data set is backed-up with a utility program and is stored on two tape volumes. Access to the entire mosaic at a later date simply requires that two tapes restore the required files.



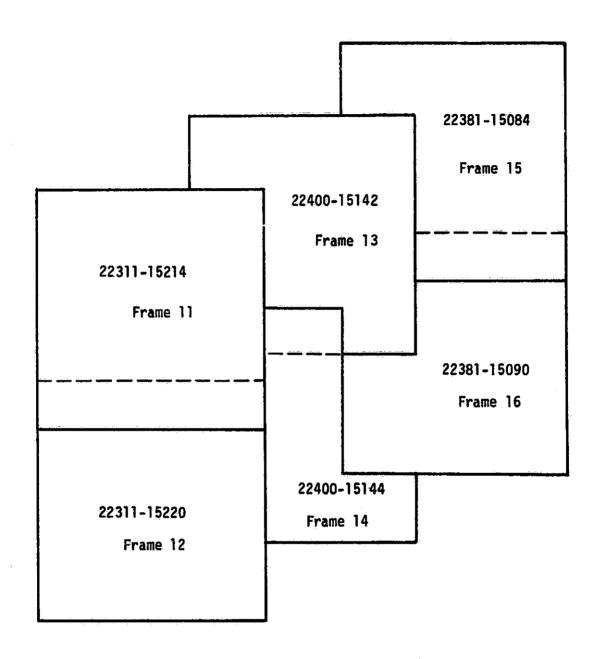
Mosaicking Arrangement UTM Zone 17. This figure depicts the order of precedence in which the individual Landsat scenes are inserted into the mosaic image space.

Figure 51



Mosaicking Arrangement UTM Zone 18. This figure depicts the order of precedence in which the individual Landsat scenes are inserted into the mosaic image space.

Figure 52



Mosaicking Arrangement UTM Zone 17. Second Date: 1981. This figure depicts the order of precedence in which the individual Landsat scenes are inserted into the mosaic space.

Figure 53

6.5 Accuracy

The accuracy of Landsat digital mosaics has been evaluated to some degree by several sources, including Goddard and Purdue University (7). Edge-to-edge mismatching is the most visible error in mosaics. Edge errors tend to encourage scrutiny and degrade the aesthetic and planimetric qualities of the final product.

6.5.1 Local: Scene to Scene

Overall, scene-to-scene mismatch in the Pennsylvania mosaic is minimal. What does exist is difficult to assess primarily because imagery of different dates was used to produce the mosaic. Those few areas that did exhibit some degree of mismatch were on the order of one to three pixels, but only for very short stretches (100 pixels). In addition, mismatched areas generally fell outside the Pennsylvania state border and did not adversely impact the project.

6.5.2 Planimetric Accuracy

From a cartographic viewpoint, the evaluation of map accuracy is a difficult procedure. Accuracy is interpreted from map specifications and standards, but several interpretations of the standards are possible depending upon the method used. The gray areas of interpretation must be acknowledged so that the relatively narrow standards are not applied inappropriately, in that they neglect the intent or spirit of the specifications.

For continuity, the United States National Map Accuracy Standards (NMAS) were applied in a limited way to evaluate the planimetric qualities of the mosaic. These standards are:

of the points tested shall be in error greater than 1/50 inch. These limits of accuracy shall apply in all cases to positions of well-defined points only. Well-defined points are those that are easily visible such as the following: monuments or markers, such as bench marks, property boundary monuments; intersections of roads, railroads, etc; features not

identifiable on the ground within close limits are not to be considered as test points within the limits quoted, even though their positions may be scaled closely upon the map. In this class would come timber lines, soil boundaries, vegetation associations. etc."

The root mean square error (RMSE) for identifiable points in a series of 7-1/2 minute quadrangles was calculated. Verification points were located in 19 quads within a 1° x 2° quadrangle in the state. There are over 800 7-1/2 minute quads in Pennsylvania, making it expensive to sample each one. For several of these quadrangles, the actual GCPs were examined and found to be excellent per specifications for the CPLBS. Line/sample values for a given point in the mosaic were located 'after the fact' on an interactive display unit with a trackball cursor and then recorded. The calculated position of that point per the UTM mapping projection grid was compared against the located point and the deltas (X,Y) noted. The RMSE was calculated by the following formulae for all points checked:

RMS =
$$\sqrt{\frac{\gamma_1^2}{n}}$$
; (1)

RMS =
$$\sqrt{\frac{x_1^2}{n}}$$
; (2)
SAMPLE(X)

$$D = \sqrt{RMS_{\gamma}^2 + RMX_{X}^2} . (3)$$

Results of these calculations are given in Table 9.

TABLE 9

		PIXELS	METERS
Delta	Line	1.13	64.4
Delta	Sample	3.49	198.9
Delta	D	3.67	209.19

A total of nineteen points were used in the verification, one point for each 7-1/2 minute quadrangle. The distribution for these points was narrow: all fell within a 1° x 2° quadrangle. While in the process of the initial verification, it was noted that certain areas of the mosaic had geometric stability problems, while others did not. Our efforts were concentrated on the problem areas.

The acceptable error for maps of the 1:250,000 scale class is 127 meters in the X and Y directions. While the line errors are well within this limit, the sample errors and derived D values are not. Those particular errors have been attributed to the Mirror Scan Velocity Profile (MSVP) of the multispectral scanner. Formulas used in the nominal corrections of the data were obtained from the published public record. The formulas are determined by instrument bench tests during system preflight checks. It is possible that if fatigue and wear in the scanner system caused the MSVP to change, then the correcting formula would change similarly. The MSVP can be compensated for during the mosaicking process but it requires an extremely dense network of GCPs, especially within the peaks and troughs of the profile. Contributing factors that inhibit proper correction are the inability to obtain sufficient correlation of GCPs because of changes in land cover, lack of actual identifiable features, and atmospheric conditions.

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